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PRELIMINARY NOTE ON A METHOD OF

ESTIMATING TRIM DRAG AT SUPERSONIC SPEED

J. Morris

Jan. 156

PRELIMINARY NOTE ON A METHOD OF ESTIMATING TRIM DRAG SIGNATURE AT SUPERSONIC SPEEDS Unit Rank Appointment

It can easily be shown that the theoretical drag, at supersonic speeds, of a two dimensional airfoil with a control surface is as follows:

Obviously the equation will have a similar form in the three dimensional case.

The first thing to establish is that the equation has the right form when compared with experimental results. The data of RM A52LO4 has been used to make this comparison and is presented in Fig. 1 and 2. It can be seen that the equation compares very well with the experimental data up to $O(=12^\circ)$ and $S=-15^\circ$; above $S=-15^\circ$, the experimental drags are lower than the equation would predict.

The object of this note is to devise a method of estimating

In the theoretical two dimensional case, the drag of the control surface is equal to the component of the normal force on the control in the flight direction, i.e.

$$\Delta G_{\epsilon} = \Delta G_{\epsilon} (\delta + \alpha) \cos \theta$$
 to the first order

where ΔC_c is the lift on the control divided by $\frac{1}{2} e^{\sqrt{2}c}$ & θ is the control leading edge sweep.

and
$$\triangle C_{\mathcal{L}} = \frac{\partial C}{\partial \mathcal{L}} (\delta + \alpha)^2 \cos \Theta = \alpha_{\mathcal{L}} (\delta + \alpha)^2 \cos \Theta$$

In the three dimension case -

Where $\Delta \zeta_{w}$ is the lift coefficient on the aircraft due to the control.

Therefore -
$$\frac{\partial C}{\partial (d+\alpha)} = K_1 a_2 \cos \Theta$$

Where $K_2 = \frac{\Delta C_2}{\Delta C_2 \omega}$

The ratio of experimental to theoretical K2 vs Mach number has been plotted in Fig. 3. From these results, it would appear that the theoretical K2's agree very well with those obtained from experiments.



The estimated K_2 's for the C-105 are shown in Fig. 4 and the experimental K_2 's from the Cornell tests are also plotted.

It is sometimes convenient to re-arrange equ. (1), substituting for ${\mathfrak A}$ from the lift equation.

We then have
$$-\zeta_0 = \zeta_{00} + \frac{\zeta_0^2}{e^{\pi}A} + \left(\frac{K_0}{a_0} + \frac{1}{e^{\pi}A} - \frac{2K_0}{a_1}\right)(a_0\delta)^2 + \left(\frac{K_2}{a_0} - \frac{1}{e^{\pi}A}\right)2\zeta_0a_0\delta - (2)$$

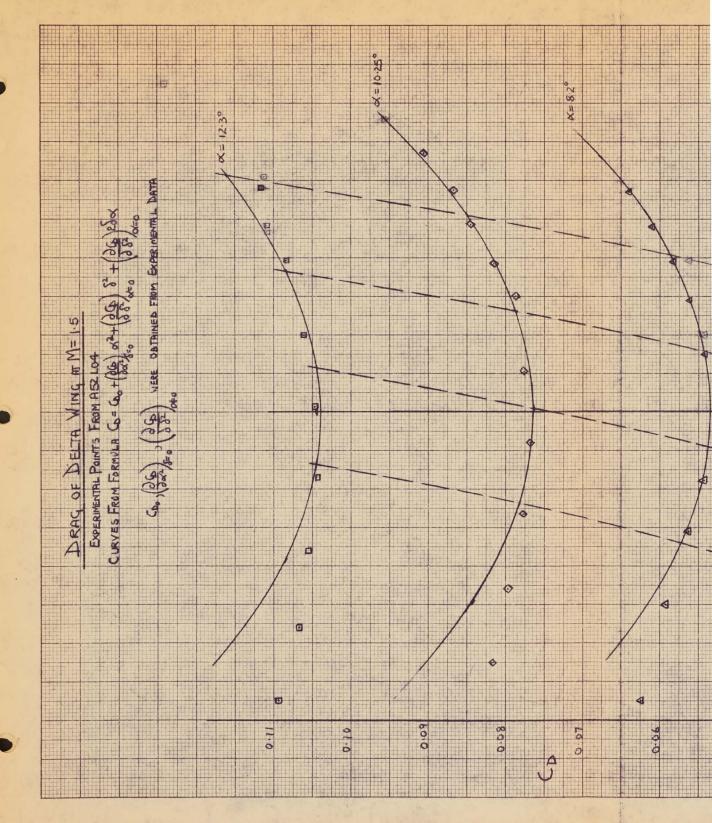
The first two terms in the above equation represent the minimum drag coefficients and the conventional induced drag and what remains are defined as the trimming drag $C_b^{\ \ \ \ \ \ }$.

The pitching moment due to controls at constant $C_{T_1} = (h_0 - h_d) \alpha_z J = C_{M} J$

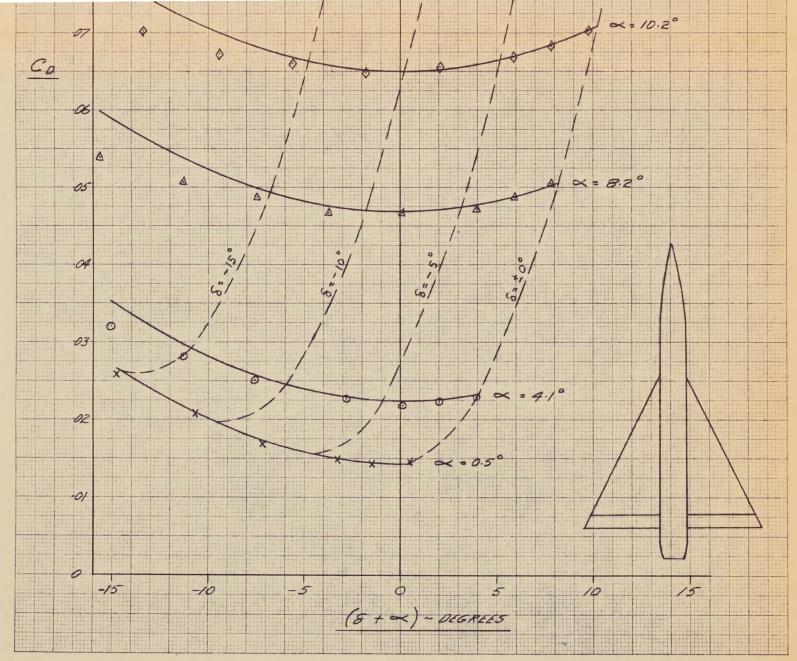
and:
$$GS = \left(\frac{\kappa_2}{\alpha_1} - \frac{2\kappa_2}{\alpha_1} + \frac{1}{e^{\frac{1}{11}A}}\right) \left(\frac{CH^6}{(h_0 - h_0)}\right)^2 + \left(\frac{\kappa_1}{\alpha_1} - \frac{1}{e^{\frac{1}{11}A}}\right) \frac{CH^6}{(h_0 - h_0)}$$
 (3)

If we include the facts that the minimum drag does not occur at $C_L = 0$ and that C_L is more generally $C_L = \alpha_1(\alpha - \kappa_s) + \alpha_1 \delta$ then the drag equation becomes $C_D = G_{\text{Min}} + \left(\frac{C_L - C_{\text{Comin}}}{c_1 \pi A}\right)^2 + \left(\frac{K_L}{\alpha_1} - \frac{2K_L}{\alpha_1} + \frac{1}{c_1 \pi A}\right) \left(\frac{C_L \delta}{K_0 - K_1}\right)^2 + \left(\frac{K_L}{\alpha_1} - \frac{1}{c_1 \pi A}\right) \left(\frac{C_L \delta}{K_0 - K_1}\right)^2 + \left(\frac{K_L}{\alpha_1} - \frac{1}{c_1 \pi A}\right) \left(\frac{C_L \delta}{K_0 - K_1}\right)^2 + \left(\frac{K_L}{\alpha_1} - \frac{1}{c_1 \pi A}\right) \left(\frac{C_L \delta}{K_0 - K_1}\right)^2 + \left(\frac{K_L}{\alpha_1} - \frac{1}{c_1 \pi A}\right) \left(\frac{C_L \delta}{K_0 - K_1}\right)^2 + \left(\frac{K_L}{\alpha_1} - \frac{1}{c_1 \pi A}\right) \left(\frac{C_L \delta}{K_0 - K_1}\right)^2 + \left(\frac{K_L}{\alpha_1} - \frac{1}{c_1 \pi A}\right) \left(\frac{C_L \delta}{K_0 - K_1}\right)^2 + \left(\frac{K_L}{\alpha_1} - \frac{1}{c_1 \pi A}\right) \left(\frac{C_L \delta}{K_0 - K_1}\right)^2 + \left(\frac{K_L}{\alpha_1} - \frac{1}{c_1 \pi A}\right) \left(\frac{C_L \delta}{K_0 - K_1}\right)^2 + \left(\frac{K_L}{\alpha_1} - \frac{1}{c_1 \pi A}\right) \left(\frac{C_L \delta}{K_0 - K_1}\right)^2 + \left(\frac{K_L}{\alpha_1} - \frac{1}{c_1 \pi A}\right) \left(\frac{C_L \delta}{K_0 - K_1}\right)^2 + \left(\frac{K_L}{\alpha_1} - \frac{1}{c_1 \pi A}\right) \left(\frac{C_L \delta}{K_0 - K_1}\right)^2 + \left(\frac{K_L}{\alpha_1} - \frac{1}{c_1 \pi A}\right) \left(\frac{C_L \delta}{K_0 - K_1}\right)^2 + \left(\frac{K_L}{\alpha_1} - \frac{1}{c_1 \pi A}\right) \left(\frac{C_L \delta}{K_0 - K_1}\right)^2 + \left(\frac{K_L}{\alpha_1} - \frac{1}{c_1 \pi A}\right) \left(\frac{C_L \delta}{K_0 - K_1}\right)^2 + \left(\frac{K_L}{\alpha_1} - \frac{1}{c_1 \pi A}\right) \left(\frac{C_L \delta}{K_0 - K_1}\right)^2 + \left(\frac{K_L}{\alpha_1} - \frac{1}{c_1 \pi A}\right) \left(\frac{C_L \delta}{K_0 - K_1}\right)^2 + \left(\frac{K_L}{\alpha_1} - \frac{1}{c_1 \pi A}\right) \left(\frac{C_L \delta}{K_0 - K_1}\right)^2 + \left(\frac{K_L}{\alpha_1} - \frac{1}{c_1 \pi A}\right) \left(\frac{C_L \delta}{K_0 - K_1}\right)^2 + \left(\frac{K_L}{\alpha_1} - \frac{1}{c_1 \pi A}\right) \left(\frac{C_L \delta}{K_0 - K_1}\right)^2 + \left(\frac{K_L}{\alpha_1} - \frac{1}{c_1 \pi A}\right) \left(\frac{C_L \delta}{K_0 - K_1}\right)^2 + \left(\frac{K_L}{\alpha_1} - \frac{1}{c_1 \pi A}\right) \left(\frac{C_L \delta}{K_0 - K_1}\right)^2 + \left(\frac{C_L$

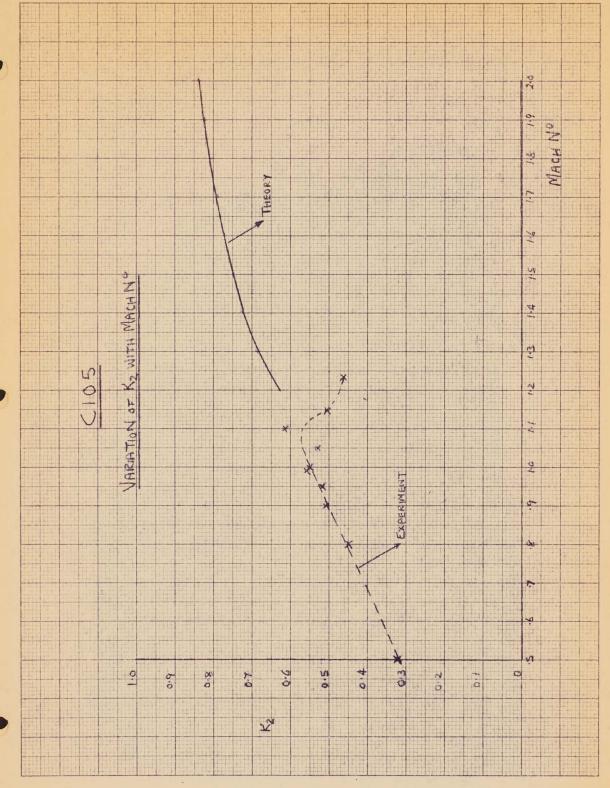
The drag coefficient vs C_L curve for the C-105 at M = 1.5 has been evaluated using the above equation and is presented in Fig. 5; the C_D vs C_L curve using the method outlined in C-105 Performance Report No. 1 is also shown.



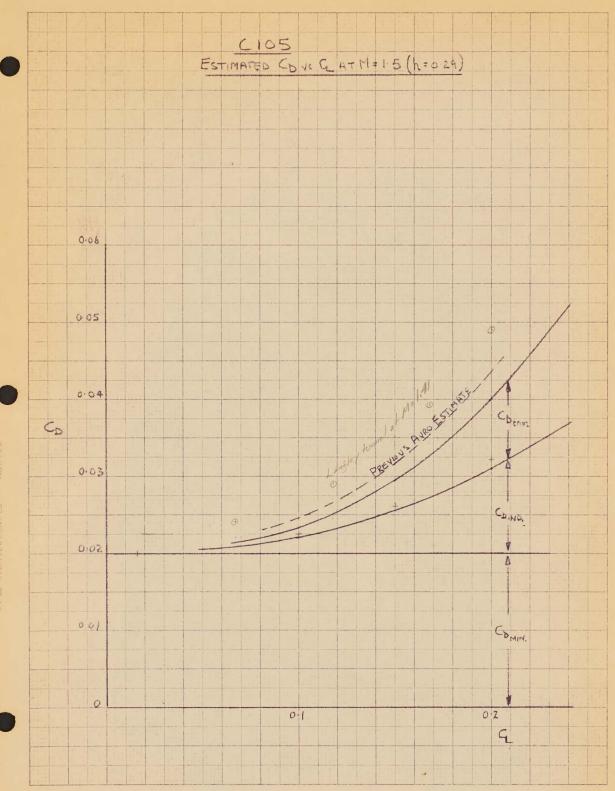
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