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Unit / Rank / Appointment A VCSS

R-THETA NAVIGATION COMPUTER

ELECTRONICS

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J.H. PARKIN BRANCH

MAY 24 1995

ANNEXE J. H. PARKIN CNRC - ICIST

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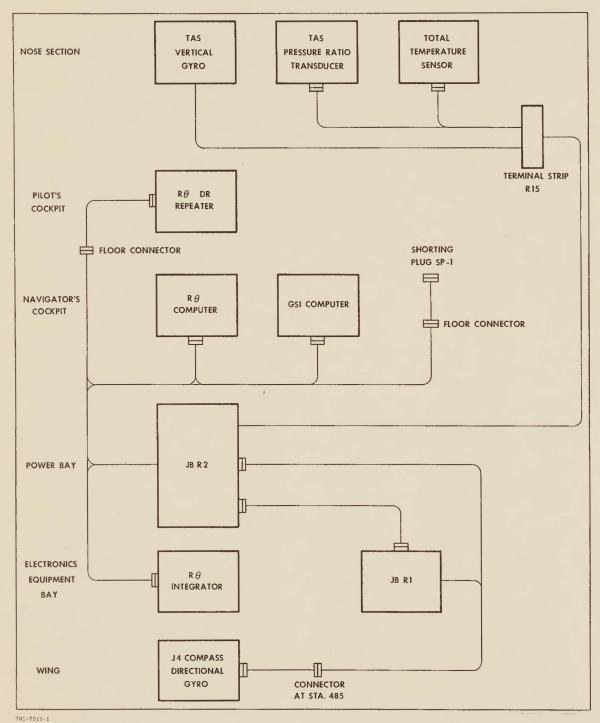


FIG. 1 R-THETA NAVIGATION COMPUTER - GENERAL ARRANGEMENT

SYSTEM DATA SHEET

SYSTEM	SUB-SYSTEM	AIRCRAFT EFF'TY	REF. NO.
ELECTRONICS	R-THETA NAVIGATION COMPUTER	25 2 01	13-3
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DESCRIPTION

Ceneral

- 1. The R-Theta (R range, Theta bearing) Navigation Computer System indicates continuously, irrespective of the aircraft track, the true bearing of and the direct distance in nautical miles to a reference point. The indicated distance is limited to 999 miles after which the system must be reset to a new reference point. In addition, during flight any point can be selected as an alternative reference, in which case the system will indicate the true bearing of, and direct distance to, the alternative reference point.
- 2. The system utilizes heading information supplied by the J4 Compass System but is otherwise independent of radio or other aids. However, provision is made to utilize such aids if required. In addition to the heading information supplied by the J4 Compass System, the computer requires the following information to compute the position of the aircraft:
- (a) True Airspeed (supplied by TAS sensing components).
- (b) Magnetic or Grid Variation (Applied manually).
- (c) Wind Speed and Direction (Applied manually).
- 3. The system consists of the following component units:
- (a) R-Theta Integrator Type 269 MK 1.
- (b) Ground Speed and Interceptor (CSI) Computer Type 269 MK 4D.
- (c) R-Theta (R-∂) Computer Type 269 MK 2.
- (d) R-Theta (R-θ) DR Repeater Type 269 MK 2.
- (e) The following TAS components which are not supplied as part of the system: Vertical gyro, pressure ratio transducer, total temperature sensor.

Integrator - Amplifier

- 4. The integrator serves as the power distributing point and interconnecting link between the component units of the R-Theta Navigation System.
- 5. Magnetic heading information from the J4 Compass and true airspeed from the pressure ratio transducer are received by the unit. The heading information and true airspeed are supplied to the GSI Computer. The heading information only is supplied to the R-Theta DR Repeater.
- 6. True heading, true track and ground speed data are received from the CSI Computer. The true heading information is supplied to the R-Theta DR Repeater. The true track and ground speed data are supplied to the R-Theta Computer.

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- 7. The unit incorporates three positional servo-amplifiers which are used in the true heading, true track and true airspeed data circuits. Also incorporated is a servo-amplifier and servo-motor unit used in the ground miles data circuit.
- 8. The integrator incorporates provision for future connection of a Radar Doppler System which automatically provides ground speed and wind drift data.

Ground Speed and Interceptor Computer

- 9. The Ground Speed and Interceptor (GSI) Computer deducts the variation correction from a magnetic heading and resolves the resultant true heading with true airspeed, wind speed and wind direction into true track and ground miles data. The magnetic heading information is received from the J4 Compass via the Integrator unit and true airspeed is received from the pressure ratio-transducer via the Integrator unit. Variation, wind speed and wind direction are applied manually by means of controls on the GSI Computer.
- 10. Magnetic heading information and the true heading are supplied via the Integrator unit to the R-Theta DR Repeater. True track and ground speed are supplied to the R-Theta Computer, via the Integrator unit.

R-Theta DR Computer

- 11. The R-Theta Computer indicates the true track of the aircraft and the true bearing of, and distance to, any selected reference point. Incorporated on the unit are the controls necessary to manipulate the system.
- 12. The bearing selected for reference can be the take-off point or a destination point. In either case a bearing pointer will indicate the selected bearing continuously, irrespective of the track of the aircraft. The bearing pointer is formed with two spaced index marks at one end and one index mark at the other. The single index mark points to the reciprocal of the bearing selected for reference. The track of the aircraft is indicated by a track pointer which is driven by tracking data received from the GSI Computer. As the track pointer and the bearing pointer are mounted on concentric shafts, aligning the track pointer between the two index marks of the bearing pointer will track the aircraft on the reference bearing to the reference point.
- 13. Due primarily to the fact that the reference bearing changes rapidly as the aircraft approaches close to the reference point, the bearing pointer is automatically rendered inoperative when the aircraft is inside a radius of two miles from the reference point. In this state an automatic reciprocal circuit becomes operative and the bearing pointer commences to fluctuate about the track indication. When the range counter reaches zero, the bearing pointer rotates through 180 degrees to the reciprocal of the track indication and fluctuates about this indication. The range counter will commence to add mileage and when the radius of two miles is passed, the bearing pointer will operate normally but will maintain the 180 degree reciprocal.
- 14. The distance to the reference point is indicated on a counter which can be set up in one of two ways. The counter can be set to zero prior to take-off in which case the counter will indicate, continuously, the direct distance in nautical miles to the take-off point. Alternatively, if the bearing pointer is preset to the destination point the counter can be preset to the mileage of the destination point

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ELECTRONICS	R-THETA NAVIGATION COMPUTER	25201	13-3

relative to the take-off point in which case the counter will indicate a decreasing mileage during flight. If an alternative reference point is selected during flight, the counter will automatically indicate the distance to the alternative reference.

- 15. The computer is set for the required bearing and range by means of a SET R θ switch, two range (R) switches and two bearing (θ) switches. When the SET R θ switch is pulled out, the range counter can be adjusted by depressing the R increase or decrease switch. Similarly, the bearing can be increased or decreased by depressing the appropriate θ switch. The selected range and bearing is locked as a reference for the computer when the SET R θ switch is depressed.
- 16. Confirmation that ground speed data is being received from the GSI Computer is provided by a green coloured indicator light which blinks continuously during computation.
- 17. Computation of an alternative reference is accomplished by inserting into the computer, as a vector, the bearing of and distance to the alternative reference from the original reference. The vector length is set up on the computer by means of a VECTOR IENGTH control and the vector bearing by means of a VECTOR BRG control. The vector can be inserted, when desired, by means of a VECTOR ADD switch. When the vector is inserted, the bearing pointer and the range counter will automatically indicate the bearing of and distance to the new reference point. It should be noted that deviation from the true track, during the time the computer is computing the alternative reference, will introduce errors into the range and bearing indications.
- 18. The vector can be cancelled at any time by pulling out the VECTOR ADD switch or, alternatively, an additional vector may be inserted. If the first vector is cancelled, the bearing pointer reverts to the original reference bearing and the range counter will be adjusted for the number of miles flown on the alternative reference. If a second vector is inserted, the first vector cancels and takes the place of the original reference. It should be noted that bearing and range will be computed from the first vector.
- 19. A counter marked VEC RECORD indicates, for reference, the vector length inserted into the computer. The counter clears when the vector is cancelled.
- 20. A memory circuit is incorporated in the computer to store ground miles information under certain conditions. The circuit is operative automatically when an alternative reference point is selected during flight, or the indicated range exceeds 999 miles. The circuit can be selected manually by means of a HOLD switch mounted on the R-Theta Computer.
- 21. The circuit is necessary due to the fact that when an alternative reference point is set up on the computer there is an indeterminate time, in which the computer is computing the new range data, when the miles flown is not counted. The memory circuit records this mileage and applies them to the counter upon the completion of the new computation. The operation of the memory circuit when 999 miles is indicated on the range counter serves to provide a warning that the original computation will be lost if a new reference point is not selected.

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- 22. Selecting the HOLD switch to the Hold position renders the range counter stationary and the memory circuit operative. This facilitates comparing computed and observed positions.
- 23. When 120 miles has been accumulated by the memory circuit, a red coloured indicator light on the computer starts to blink. When 150 miles has been accumulated, the indicator light remains on continuously denoting that the original computation has been lost.
- 24. During the time the memory circuit is operative, deviation from the indicated track will introduce errors into the computed indications.

R-Theta DR Repeater

25. The R-Theta DR Repeater is slaved to the R-Theta Computer to indicate the true track, reference bearing and range. A range counter reset control is provided to preset the range counter in agreement with the R-Theta Computer range counter. In addition, a selector switch is provided which permits magnetic heading or true heading, in lieu of true track, to be indicated by the track pointer. The magnetic heading and the true heading are received directly from the integrator unit.

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COMPONENT DATA SHEET

SYSTEM		SUB-SYSTEM		COMPON	NENT	REF. NO.		
ELECTRONICS		R-THETA NAVIGATI COMPUTER	ON	Integrator - Type 269		13-3-1		
AVRO PART NO.		MANUFACTURER MAN'F'R'S PART NO.			AIRCRAFT EFFECTIVITY			
	PS	GC Applied Research (RCAF Supply)	C Applied Research (RCAF Supply)			25201		
OVERHAUL LIFE:	KNOWN	4	ES	TIMATED- 500	hours			
FUNCTION	miles of heading integra	se a servo-motor and data circuit and threat, true track and truator serves as the irent units of the syst	e servo- le airspe laterconne	amplifiers used ed circuits. In	in the true addition the			
LOCATION	Electro	onics Equipment Bay -	- LH side					
ACCESS					м	EN X MINUTES		
		e and lower the Elect tre access door - 33						
REPLACEMENT PROC	EDURE				М	EN X MINUTES		
		d secure connector RI it to mounting and se						
NI-343-2-5	-11-							

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INSPECT	ION		MEN X MINUTES
		Check that the connector is securely and properly connected. Check that the unit is securely mounted.	
FUNCTIO	NAL CHECKS		MEN X MINUTES
GROUND	HANDLING AND GR	OLIND TEST FOLIPMENT	
		COND 1231 EQUI MENT	
		Pitot and Static pressures simulator. Navigation System Test Set - Type T601, RC Stop Watch.	CAF Ref. 6C/970
	TOOLS TO REMOVE	Pitot and Static pressures simulator. Navigation System Test Set - Type T601, RC Stop Watch.	CAF Ref. 6C/970
		Pitot and Static pressures simulator. Navigation System Test Set - Type T601, RC Stop Watch.	CAF Ref. 6C/970
	TOOLS TO REMOVE	Pitot and Static pressures simulator. Navigation System Test Set - Type T601, RC Stop Watch.	CAF Ref. 6C/970
SPECIAL	TOOLS TO REMOVE	Pitot and Static pressures simulator. Navigation System Test Set - Type T601, RC Stop Watch.	CAF Ref. 6C/970
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SYSTEM		SUB-SYSTEM		COMPONENT		REF. NO		
ELECTRON ICS		R-THETA NAVIGAT COMPUTER	ION	Integrator	Mounting	13-3-2		
AVRO PART NO.		MANUFACTURER MAN'F'R'S PART NO.			AIRCRAFT	EFFECTIVIT		
	PSC	Applied Research (RCAF Supply)	Applied Research RCAF Supply)			25201		
OVERHAUL LIFE: K	NOWN-	-	ES.	TIMATED- 500	hours			
FUNCTION Mc	ounts t	the Integrator Unit	of the s	ystem.				
LOCATION	lectron	nics Equipment Bay -	LH side	•		,		
ACCESS					N	MEN X MINUTE		
Da	ay, cer	tre access door - 3	3 camioc	5.				
REPLACEMENT PROCE	DURE				N	IEN X MINUTE		
F	it mour	nting to airframe wi	th four 1	mounting bolts.				

INSPECTI	ON								MEN X	MINUTES
			Che	ck that th ted and is	e mounting not disto	g is secur	ely			
										
FUNCTION	NAL CHECK	S						-	MEN X	MINUTES
										*
GROUND	HANDLING	AND GRO	UND TEST	EQUIPMEN	Т					
SPECIAL	TOOLS TO	REMOVE O	R SERVICE							
REMARKS	3									
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SYSTEM ELECTRONICS		SUB-SYSTEM R-THETA NAVIGATION COMPUTER		COMPON Ground Spe Interceptor Type 269 M	ed and Computer	REF. NO. 13-3-3
AVRO PART NO.		MANUFACTURER PSC Applied Research (RCAF Supply)		'R'S PART NO. 1-02731		EFFECTIVITY 201
OVERHAUL LIFE:	KNOWI	V-	ES	TIMATED- 500	hours	
FUNCTION	resolve speed	uct a variation corre e the resultant true and direction into tr is required by the R-	heading ue track	with true airspp and ground mile	ed, wind	
LOCATION	Instru	ment panel - Rear coc	kpit.			
ACCESS	3.0 m	<u> </u>			МІ	EN X MINUTES
	Unobst	ructed.				
REPLACEMENT PROG	CEDURE				МЕ	EN X MINUTES
	Fit and Fit unscrews	d secure connector Rl it to instrument pane	.046/l-(K l with f	03-21-30SN). our mounting		

INSPECTION		MEN X MINUTES
	Check that the connector is securely and properly fitted. Check that the unit is securely mounted.	
FUNCTIONAL CHECKS		MEN X MINUTES
GROUND HANDLING AND GRO	UND TEST EQUIPMENT	
	Pitot and Static pressures simulator. Navigation System Test Set, Type 601 RCAF Ref	c. 6c/970
SPECIAL TOOLS TO REMOVE O	Pitot and Static pressures simulator. Navigation System Test Set, Type 601 RCAF Ref Stop Watch.	e. 60/970
	Pitot and Static pressures simulator. Navigation System Test Set, Type 601 RCAF Ref Stop Watch.	c. 60/970
	Pitot and Static pressures simulator. Navigation System Test Set, Type 601 RCAF Ref Stop Watch.	c. 6c/970
SPECIAL TOOLS TO REMOVE O	Pitot and Static pressures simulator. Navigation System Test Set, Type 601 RCAF Ref Stop Watch.	60/970
SPECIAL TOOLS TO REMOVE O	Pitot and Static pressures simulator. Navigation System Test Set, Type 601 RCAF Ref Stop Watch.	e. 60/970
SPECIAL TOOLS TO REMOVE O	Pitot and Static pressures simulator. Navigation System Test Set, Type 601 RCAF Ref Stop Watch.	c. 60/970
SPECIAL TOOLS TO REMOVE O	Pitot and Static pressures simulator. Navigation System Test Set, Type 601 RCAF Ref Stop Watch.	e. 60/970
SPECIAL TOOLS TO REMOVE O	Pitot and Static pressures simulator. Navigation System Test Set, Type 601 RCAF Ref Stop Watch.	e. 60/970

		SUB-SYSTEM		COMPON	IENT	REF. NO
ELECTRONICS		R-THETA NAVIGAT COMPUTER	ION	R-Theta Comput 269 MK 2		13-3-4
		MANUFACTURER C Applied Research (RCAF Supply)		MAN'F'R'S PART NO. 101-02730		EFFECTIVIT 201
OVERHAUL LIFE:	KNOWN	1 –	ES	TIMATED- 500	hours	
FUNCTION	the tru	tes the true track of ne bearing of, and di the controls necesse	stance t	o, any selected .	reference po	
LOCATION	Instrum	ment panel - Rear coc	kpit.			
ACCESS	UP-W				М	EN X MINUTE
	Unobstr	ructed.				
REPLACEMENT PRO	CEDURE				ME	EN X MINUTE
	Fit and	d secure connector Rld secure unit to instruction bolts.	047/1 (K rument p	03-21-30SV). anel with		

INSPECTION		MEN X MINUTES
	Check that the connector is securely and properly fitted. Check that the unit is securely mounted.	
FUNCTIONAL CHECKS		MEN X MINUTES
GROUND HANDLING AND GROUND 1		
GROUND HANDLING AND GROUND I	Pitot and Static pressures simulater. Navigation System Test Set Type 601-RCAF Ref 6C/970.	
SPECIAL TOOLS TO REMOVE OR SER	VICE	
REMARKS		
ISSUE 1		
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SYSTEM		SUB-SYSTEM		COMPOR	JENT	REF.	NO
ELECTRONICS		R-THETA NAVIGATI		DR Repeater Ty	2-21-21		
Ballo Tron 100	, p	COMPUTER	·Off	Die Ropodool 19	pe zo, ini z	100	
AVRO PART NO.	*	MANUFACTURER	MAN'F	R'S PART NO.	AIRCRAFT	EFFECT	IVIT'
	PSC Applied Research 101-02624 (RCAF Supply)		2	25201			
OVERHAUL LIFE:	KNOWI	V-	ES.	TIMATED- 500	hours		
FUNCTION	bearin a swit	Ve to the R-Theta Com g of and distance to ch is provided which u of true track, to b	a select	ed reference poi magnetic heading	nt. In add: or true her	ition	
LOCATION							
	Instru	ment Panel - Front Co	ekpit.				
ACCESS				· · · · · · · · · · · · · · · · · · ·	N	IEN X MIN	IUTE
	Unobst	ructed.					
					*		
REPLACEMENT PRO	CEDURE				M	EN X MIN	UTE
		d secure connector Rl it to instrument pane					

INSPECT	TION				MEN >	MINUTES
		Check that the properly fits Check that the	ted.			
FUNCTIO	NAL CHECKS				MEN >	MINUTES
GROUNE	HANDLING AND GROUND	TEST EQUIPMEN	г			
		Pitot and Sta Navigation Sy Ref. 60/970.				
SPECIAL	TOOLS TO REMOVE OR SE	RVICE		*		
REMARK	S					
ISSUE	1					

COMPONENT DATA SHEET

					1000	DEE
	SYSTEM SUB-SYSTEM			COMPON		REF. NO.
E LECTRONICS		R-THETA NAVIGATI COMPUTER	ON	Shorting Plug SP-1		13-3-6
AVRO PART NO.		MANUFACTURER	MAN'F	R'S PART NO.	AIRCRAFT	EFFECTIVITY
7-1352-85	Car	nnon Electric Canada Ltd.	K02-21-30SN 2			201
OVERHAUL LIFE:	KNOWN	V -	ES	TIMATED- 500	hours	
FUNCTION	Complet which	tes the computer circ facilitates the conne	uits con ction of	nected to a rece ground test equ	ptacle ipment.	
LOCATION	RH Cons	sole in Rear Cockpit.				
ACCESS					м	EN X MINUTES
REPLACEMENT PROG	CEDURE				М	EN X MINUTES
		lug with potting comp t and secure plug to :		le on RH		
!!-9433-2-5						

INSPECTION	MEN X MINUTES
Check that the plug is securely and properly fitted.	
FUNCTIONAL CHECKS	MEN X MINUTES
GROUND HANDLING AND GROUND TEST EQUIPMENT	
	7
SPECIAL TOOLS TO REMOVE OR SERVICE	
REMARKS	
ISSUE 1	
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