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A V ROE CANADA LIMITED

MALTON - ONTARIO

TECHNICAL DEPARTMENT (Aircraft)

AIRCRAFT Arrow I

REPORT NO 70/SIMUL/14

FILE NO

NO OF SHEETS 60

TITLE:

GENERAL INTRODUCTION TO THE
ARROW FLIGHT SIMULATOR

PREPARED BY



DATE May 1958

CHECKED BY

DATE

SUPERVISED BY

DATE

APPROVED BY

DATE

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REPORT NO. _____

SHEET NO. 1

AIRCRAFT _____

The Arrow Flight
Simulator

PREPARED BY _____

DATE _____

D. J. Foster

Feb 58.

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INTRODUCTION

The Arrow Flight Simulator has been designed to provide a replica of the aircraft's performance over the range of flight conditions between take off and Mach 2.5 and up to altitudes of 80,000'. All known significant cross-coupling effects have been included and the variation of aerodynamic derivatives with Mach No., Altitude and incidence have been allowed for.

In conjunction with the cockpit and control system simulation, it can be used familiarize pilots with the performance of the aircraft, especially from the point of view of instrument display. Alternatively, it may be used in conjunction with a simulation of the radar system to investigate fire control problems. Two ways in which the simulator has already been used were to check out the suitability of the control system for the aircraft, by linking the computer to the B-1 rig, and to check the behaviour of the controls and damping system installed in the first aircraft, by linking the simulator to the aircraft control surfaces and providing an auxiliary instrument panel inside the cockpit.



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EQUATIONS OF MOTION

In the course of simulation, the six equations of motion are formulated, specifically the lift, drag, sideforce, rolling moment, yawing moment and pitching moment equations. Of these, the first two equations are in the wind axes system, and the remaining four in the body axes system. Once the lift and drag forces have been obtained, they are resolved into their components in the body axes system. This has been done because, although the body axes system is more suitable for simulation, people in general are more familiar with the concepts of lift and drag than of normal force and axial force.

The principal problem to be overcome in mechanizing the force and moment equations was that some of the aerodynamic derivatives were functions of three variables:- Mach Number, Altitude and Incidence. By examining the variations, it was concluded that an acceptable approximation would be to separate the variables, and take sums and multiples of functions of each of the three variables.



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LIFT COEFFICIENT

$$C_L = C_{L_{\alpha E}} (\alpha - \alpha_{0E}) + C_{L_{\delta e E}} \delta e$$

$$\text{where } C_{L_{\alpha E}} = C_{L_{\alpha R}} (1 - f_1 g_1)$$

$$\alpha_{0E} = \alpha_{0R} (1 - f_2 g_2)$$

$$C_{L_{\delta e E}} = C_{L_{\delta e R}} (1 - f_3 g_3)$$

$C_{L_{\alpha R}}$, $f_1 \alpha_{0R}$, f_2 , $C_{L_{\delta e R}}$, f_3 are Mach Functions.

g_1 , g_2 , g_3 , are Altitude Functions.

Drag Coefficient

$$C_D = C_{D_0} + C (C_L + E)^2 + G C_L \delta e + H \delta e^2$$

where C_{D_0} , C , E , G , and H are Mach Functions

Sideforce Coefficient

$$C_Y = C_{Y_{\beta E}} \beta + C_{Y_{\delta r E}} \delta r$$

$$\text{where } C_{Y_{\beta E}} = C_{Y_{\beta R}} + C_{Y_{\beta \alpha}} \alpha - (f_{20} + f_{21} \alpha) g_{20}$$

$$C_{Y_{\delta r E}} = C_{Y_{\delta r R}} (1 - f_{19} g_{19})$$

$C_{Y_{\beta R}}$, $C_{Y_{\beta \alpha}}$, f_{20} , f_{21} , $C_{Y_{\delta r R}}$, f_{19} are Mach Functions

g_{20} , g_{19} are Altitude Functions

Pitching Moment Coefficient

$$C_M = C_{M_{0E}} + (c.g. - a.c.) C_{L_{\alpha E}} (\alpha - \alpha_{0E}) + C_{M_{\delta e E}} \delta e + C_{M_q} \frac{q.c}{2v} + C_{M_{\dot{\alpha}}} \frac{\dot{\alpha}.c}{2v}$$

$$\text{where } C_{M_{0E}} = C_{M_{0R}} (1 - f_9 g_9)$$

$$C_{M_{\delta e E}} = C_{M_{\delta e R}} (1 - f_{10} g_{10})$$



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$C_{M_{OR}}, f_9, C_{M_{\delta eR}}, f_{10}, C_{M_q}, C_{M_{\dot{\alpha}}}, (c.g - a.c)$ are Mach Functions
 g_9, g_{10} , are Altitude Functions

Yawing Moment Coefficient

$$C_n = C_{n_{\beta E}} \beta + C_{n_{\delta r E}} \delta r + C_{n_{\delta a E}} \delta a + C_{n_p} \frac{pb}{2v} + C_{n_r} \frac{rb}{2v}$$

$$\text{where } C_{n_{\beta E}} = C_{n_{\beta R}} + C_{n_{\beta \alpha}} \alpha + 1(f_{20} + f_{21} \alpha) g_{20}$$

$$C_{n_{\delta r E}} = (C_{n_{\delta r R}} + \alpha C_{n_{\delta r \alpha}}) (1 - f_{22} g_{22})$$

$$C_{n_{\delta a E}} = (C_{n_{\delta a R}} + \alpha C_{n_{\delta a \alpha}}) (1 - f_{23} g_{23})$$

where $C_{n_{\beta R}}, C_{n_{\beta \alpha}}, 1, f_{20}, f_{21}, C_{n_{\delta r}}, C_{n_{\delta r \alpha}}, C_{n_{\delta a}}, C_{n_{\delta a \alpha}}, f_{23}$ are Mach Functions
 g_{20}, g_{22}, g_{23} are Altitude Functions

Rolling Moment Coefficient

$$C_l = C_{l_{\beta E}} \beta + C_{l_{\delta r E}} \delta r + C_{l_{\delta a E}} \delta a + C_{l_p E} \frac{pb}{2v}$$

$$\text{where } C_{l_{\beta E}} = C_{l_{\beta R}} + \alpha C_{l_{\beta \alpha}} - 2(f_{20} + f_{21} \alpha) g_{20}$$

$$C_{l_{\delta a E}} = C_{l_{\delta a R}} (1 - f_{23} g_{23})$$

$$C_{l_{\delta r E}} = C_{l_{\delta r R}} (1 - f_{24} g_{24})$$

$$C_{l_p E} = C_{l_p R} (1 - f_{26} g_{26})$$

$C_{l_{\beta R}}, C_{l_{\beta}}, f_{20}, f_{21}, C_{l_{\delta a R}}, f_{24}, C_{l_{\delta r R}}, C_{l_p R}, f_{23}, f_{26}$ are Mach Functions
 $g_{20}, g_{23}, g_{24}, g_{26}$ are Altitude Functions

Although the derivatives were generated in the way just described, when it came to mechanizing the equations of motion in the computer, it was not always convenient to use the derivative values. One reason was that the derivatives might not be correctly scaled. Another was that the computer had to generate forces and moments rather than



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just derivatives, so in some cases the Mach Number times the
derivativewas scaled. Scaling was necessary because the functions
of Mach No. and altitude were obtained from tapped potentiometers, and
a value of greater than 1.0 could never be obtained, but for reasons of
accuracy a value of as near 1.0 as possible was desireable.



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Physical Constants

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(a) Aircraft

Provision has been made in the computer for inserting aerodynamic derivatives pertinent to the centre of gravity being located at either 29% or 31% of the mean aerodynamic chord. Due to the difficulties involved in scaling the equations of motion, the same physical constants for the aircraft inertias have been used for either centre of gravity position.

Wing Area	S	1225 ft ²
Wing Span	b	50 ft
Wing Mean Aerodynamic Chord	c	30.22 ft
Weight	W	55,000 lb.
Mass	M	1710 slugs
Moment of inertia in roll	I _x	75,200 slug ft ²
Moment of inertia in pitch	I _y	389,000 slug ft ²
Moment of inertia in yaw	I _z	453,000 slug ft ²
Product of inertia (yaw-roll coupling)	I _{xz}	11,200 slug ft ²

(b) Atmospheric (Sea Level)

Speed of sound	a ₀	1116 ft/sec
Density	ρ ₀	.00238 slugs/ft ³
Pressure	p ₀	2116 lb/ft ²
Ratio of Specific heats	γ	1.40



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Equations of Motion

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Normal

$$\dot{\alpha} = \frac{p\beta}{57.3} + q + \frac{57.3}{v} \left\{ g \cos \theta \cos \phi - \frac{\dot{v}\alpha}{57.3} + \frac{\sum F_z}{M} \right\}$$

Axial

$$\dot{v} = \frac{v\alpha}{(57.3)^2} (-q + \dot{\alpha}) - \frac{g \sin \theta}{57.3} + \frac{T \cos i}{M} + \frac{\sum F_x}{M}$$

Sideslip

$$\dot{\beta} = \frac{\alpha p}{57.3} - r + \frac{57.3}{v} \left(\frac{-\dot{v}\beta}{57.3} \right) + g \cos \theta \sin \phi + \frac{\sum F_y}{M}$$

Roll

$$\dot{p} = \frac{I_{xz}}{I_x} (r + \frac{pq}{57.3}) + \frac{57.3}{I_x} \Sigma L$$

Yaw

$$\dot{r} = \frac{I_{xz}}{I_z} \dot{p} + \frac{I_x - I_y}{I_z} \frac{pq}{57.3} + \frac{57.3}{I_z} \Sigma N$$

Pitch

$$\dot{q} = \frac{I_z - I_x}{I_y} \frac{rp}{57.3} - \frac{I_{xz}}{I_y} \cdot \frac{p^2}{57.3} + \frac{57.3eT}{I_y} + \frac{57.3}{I_y} \cdot \Sigma M$$

In the above equations, all angles and angular rates are in degrees.



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Multiplication

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Because of the nonlinear character of the equations of motion, particularly when the speed and altitude are variable, a large number of multiplications were required. These multiplications were performed by using servos and ganged potentiometers. In general, the multiplications could be separated into two distinct types.

- (1) The multiplication of two quantities which occurred as voltages in the computer.
- (2) The multiplication of two quantities, one of which occurred as a voltage in the computer and the other was a function of a voltage in the computer.

For the first type, a servo motor was driven by one variable such that its angular rotation from a reference position was proportional to the variable. By exciting one of the ganged potentiometers with the second variable and driving the wiper by the servo motor, a voltage was picked off which was proportional to the product of the two quantities.

The second type of multiplication may be most easily seen if we first consider how the function of a variable was generated. As before, the servo motor was positioned such that its rotation from some reference position was proportional to the applied variable.



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Multiplication

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The wiper moved around a potentiometer as the servo motor rotated, but the potentiometer had thirteen tap points, each of which was taken to a printed circuit card. On this card were three bars, one carrying a positive reference voltage, one carrying the negative of this reference voltage and the third grounded. By connecting each of the thirteen taps of the potentiometer to one of the three bus bars through an appropriate resistor any arbitrary function of the variable driving the servo motor could be obtained. The wiper would pick off the value of the function appropriate to the input variable. If the reference voltage were now replaced by a second variable, then the wiper would pick off a voltage proportional to the product of this second variable and the function of the variable driving the servo.



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AIRCRAFT:

ARROW SIMULATOR.

DETAILS OF
MACH & ALTITUDE
FUNCTION CARDS.

PREPARED BY

D. J. Fisher

CHECKED BY

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April 58

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Card No.	Derivative or Function	Scale Factor	Load Resistor	Input	Output
1	Mach Follow-up	.4	1.0	-100v	40M
2	$CL_{\alpha R}$	10/57.3	1.0	$-2(\alpha - \alpha_0)$	-20CL
3	$CL_{\alpha R} f_1$	40/57.3	4.0	$+2(\alpha - \alpha_0) g_1$	-20CL
4	$CL_{\delta e}$	40/57.3	4.0	$+2\delta e''$	+40CL
5	$CL_{\delta e} f_3$	40/57.3	4.0	$-2\delta e'' . g_3$	40CL
6	$CD_0 + CE^2$	20	10.0	+100v	200C _D
7	C	2	0.5	50CL ²	200C _D
8	C.E	40	5.0	50CL(+&-)	200C _D
9	.G	-200	2.0	2CL. δe	200C _D
10	H	10,000	4.0	$4\delta e^2/50$	200C _D
11					
12	f ₁₁	-0.2	5.0	100v	20f ₁₁
13	CM ₀	20.2	4.0	-100v	$-p_0 \dot{q}/16pM^2$
14	CM ₀ f ₉	50.5	5.0	+50.g ₉	$-p_0 \dot{q}/16pM^2$
15	$-2(a.c-c.g)/\bar{c}$	5.05	0.4	40CL(α)	$-p_0 \dot{q}/16pM^2$
16	$2CM_{\delta e}$	-2.2	0.5	$2\delta e'$	$-p_0 \dot{q}/16pM^2$
17	$2CM_{\delta e} f_{10}$	-8.8	2.0	$-2\delta e' g_{10}$	$-p_0 \dot{q}/16pM^2$
18	CM _q	-.1907M	1.0	$-apq/a_0 p_0$	$\dot{q}/10$
19	CM _{α}	1.907M/5	2.0	$ap\dot{\alpha}/a_0 p_0$	$\dot{q}/10$
20	$-1CY_{\beta R}$	-1.58	1.0	$2\beta M^2 p/p_0$	Y/10,000
21	$CY_{\beta VR}$	-1.58	1.0	$2\beta M^2 p/p_0$	-YV/10,000
22	$CY_{\alpha \beta}$	.632	1.0	$5\alpha \beta M^2 p/57.3 p_0$	-YV/10,000
23	f ₂₀	-3.95	1.0	$-2\beta M^2 p/p_0$	ETL/4000g ₂₀
24	f ₂₁	-1.58	1.0	$5\alpha \beta M^2 p/57.3 p_0$	ETL/4000g ₂₀
25	CY _{δr}	7.90	1.0	$2\delta r M^2 p/p_0$	Y/2000



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Arrow Simulator

Details of Mach and
Altitude Function cards

PREPARED BY

DATE

D. J. Foster

April 1958

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Card No	Derivative of Function	Scale Factor	Load Resistor	Input	Output
26	$CY_{\delta r f 19}$	7.90	1.0	$-2\delta r M^2 p \cdot g_{12}/p_0$	$Y/2000$
27-2	$Cn_{\beta R}$	18.0	1.8	$2\beta M^2 p/p_0$	$\dot{r}/10$
28-1	$Cn_{\alpha \beta}$	2.00	0.5	$-5\alpha \beta M^2 p/57.3 p_0$	$\dot{r}/10$
29-2	$Cn_{\delta r}$	-20.0	2.0	$-2\delta r M^2 p/p_0$	$\dot{r}/10$
30-0	$Cn_{\delta r \alpha}$	25.0	5.0	$-2\delta r M^2 p/p_0$	$-57.3 \dot{r}/20\alpha$
31	f_{22}	0.5	1.0	$-2\delta r M^2 p g_{22}/p_0$	$\delta r M^2 p/p_0$
32	$Cn_{\delta a R}$ Mach	-50.0	5.0	$-2\delta a M^2 p/p_0$	$\dot{r}/10$
33	Follow-up	.4	1.0M	-100v	40M
34	$Cn_{\alpha \delta a}$	10.0 125	2.0	$-2\delta A M^2 P$	$57.3 \dot{r}''/\alpha \times 10$
35	f_{23}	.25	1.0	$-2\delta A g_{23} M^2 p/p_0$	$-1/2\delta A g_{23} 23 M^2 p/p_0$
36-2	$Cn_{r \cdot M}$	2.243	5.0	$-a_p/a_{\beta} p_0 \cdot r$	$\dot{r}/10$
37-1	$Cn_{p \cdot M}$	8.97	5.0	$a_p/a_{\beta} p_0 \cdot p/4(+8-)$	$\dot{r}/10$
38					
39	Cl_{β}	-7.537	0.5	$-2\beta M^2 p/p_0$	$\dot{p}/40$
40	$Cl_{\alpha \beta}$	-1.2059	0.2	$\frac{-5\alpha \beta}{57.3} M^2 p/p_0$	$\dot{p}/40$
41	$Cl_{\delta r R}$	75.37	5.0	$2\delta r M^2 p/p_0$	$\dot{p}/40$
42	$Cl_{\delta r \cdot f_{24}}$	75.37	5.0	$-2\delta r \cdot M^2 p/p_0 g_{24}$	$\dot{p}/40$
43	$Cl_{\delta a}$	-7.537	0.5	$-2\delta A M^2 p/p_0$	$\dot{p}/40$
44-2	Elastic tail moment arm	.05059	4.0	E.T.L. $/10^3$	$\dot{r}/10$
45	$Cl_{p R \cdot M}$	-1.080	0.4	$-a_p/a_{\beta} p_0 \cdot \frac{p}{4}$	$\dot{p}/40$
46	$M \cdot Cl_{p R \cdot f_{26}}$	-1.080	0.4	$a_p/a_{\beta} p_0 \cdot p/4 g_{26}$	$\dot{p}/40$
47	$Ch_{\delta E}$	12.990	5.0	-100v	$-H_E/2,000$
48	$\cdot Ch_{\delta E}$	-25.98	0.2	$-2\delta_e$	$-H_E/2,000$
49	$Ch_{\alpha E}$	-64.95	0.5	2α	$-H_E/2,000$
50	$Ch_{\delta A}$	10.794	2.5	-100v	$-H_A Port/1,000$



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Altitude Function Cards

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Card No	Derivative or Function	Scale Factor	Load Resistor	Input	Output
51	$Ch_{\delta A}$	-21.588	0.1	$-2\delta_A$	$-HA/1,000$
52	$Ch_{\alpha A}$	-21.588	0.1	2α	$-HA/1,000$
53	Ch_{β}	93.78	0.2	$2\beta M^2 P/P_0$	$HR/500$
54	$Ch_{\delta R}$	93.78	0.1	$-2\delta_R M^2 P/P_0$	$HR/500$
55	M	0.4	1.0	20M	$8M^2$
56	M	0.4	1.0	$8M^2$	$3.2M^3$
57	$f(M)/M^2 \cdot P_0$	1/4,000	1.0	$40M^2 P/P_0$	$qc/100$
58	α_0	0.2	10.0	100v (+&-)	$2\alpha_0$
59	αf_2	0.4	10.0	-50g ₂	$2\alpha_0$
60	$CM_{\delta e}^2$	.00630	2.0	$-4\delta e^2/50$	$1/16 q^1 \frac{P_0}{P} \cdot \frac{1}{M^2}$
61	$Ch_{\delta A}$	-43.176	5.0	-100v	$-HA/1,000$
62	Ch_{α}	-35.866	0.25	-57.3p/v	$-HA/1,000$
63-1	$CY_{\alpha\beta}$	-72.6	2.0	$\frac{5\alpha\beta}{57.3} M^2 \frac{P}{P_0}$	$-FY/10,000$
64	Altitude Follow-up	1/80,000	1.0M	-100v	$h/3,200$
65	g_1	1	1.0	$-2(\alpha - \alpha_0)$	$-2(\alpha - \alpha_0) g_1$
66	g_3	1	1.0	$2\delta e''$	$2\delta e'' g_3$
67	g_9	1	1.0	-100v	$-100 g_9$
68	g_{10}	1	1.0	$K_1 CM_{\delta e} + K_2 CM_{\delta e}^2$	Input. g_{10}
69	g_{19}	1	1.0	$28r M^2 P/P_0$	Input. g_{19}
70	g_{20}	1	1.0	$K\beta (f_{20} + f_{21}\alpha)$	$-E.T.L./1,000$
71	g_{22}	1	1.0	$2\delta r M^2 P/P_0$	Input. g_{22}
72	g_{23}	1	1.0	$2\delta A M^2 P/P_0$	Input. g_{23}
73	g_{24}	1	1.0	$2\delta r M^2 P/P_0$	Input. g_{24}
74	g_{26}	1	1.0	$-a_p/a_0 P_0 p/4$	Input. g_{26}



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AIRCRAFT

Arrow Simulator

Details of Mach and
Altitude Function Cards

PREPARED BY

DATE

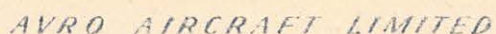
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Card No	Derivative or Function	Scale Factor	Load Resistor	Input	Output
76	ξ_{30}	1/20,000	5.0	-100	TM/1,000
77	ξ_{31}	1/10,000	2.0	20M	TM/1,000
78	ξ_{32}	-1/8,000	1.0	$8M^2(-k+)$	TM/1,000
79	ξ_{33}	1/100,000	10.0	-100	$T_{AB}/10,000$
80	ξ_{34}	-1/100,00	2.0	$20M(-k+)$	$T_{AB}/10,000$
81	ξ_{35}	1/80,000	1.0	$8M^2$	$T_{AB}/10,000$
82	ξ_{36}	-1/32,000	1.0	$-3.2M^3$	$T_{AB}/10,000$
83					
84	a	500	1.0	-V/50	-10M
85	$\sqrt{a}$	1.0	1.0	V/50	$\sqrt{10}/50$
86	$a\rho/a_0\rho_0$	1.0	1.0	-p/4	Input, $a\rho/a_0\rho_0$
86	$a\rho/a_0\rho_0$	1.0	1.0	q	Input, $a\rho/a_0\rho_0$
88					
89	$a\rho/a_0\rho_0$	1.0	1.0	α	Input, $a\rho/a_0\rho_0$
90	$a\rho/a_0\rho_0$	1.0	1.0	$p\alpha$	Input, $a\rho/a_0\rho_0$
91	$a\rho/a_0\rho_0$	1.0	1.0	r	Input, $a\rho/a_0\rho_0$ (replacing 81)
92	ξ_2	1.0	1.0	100	$100g_2$
93	P/P ₀	1.0	1.0	$-8M^2$	$-8M^2 P/P_0$
94					
95					
96					



TECHNICAL DEPT. (AIRFRAME)

C. G. POSITION . 290

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SHEET . . . 2.1

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TECHNICAL DEPT. (AIRFRAME)

AIRCRAFT - Arrow Simulator

WEIGHT . . . 55,000 lb.

C. G. POSITION 29a

REPORT NO. 70/Sim./14

SHEET - 2.2

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TECHNICAL DEPT. (AIRFRAME)

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AIRCRAFT - Arrow Simulator

WEIGHT 55,000 lb.

C. G. POSITION 29c

PREPARED BY - D. J. Foster

Card No.	1	2	3	4	5	6	7	8	9
Derivative Function	CM _x	CY _{PR}	CY _{PRV}	CY _{PRV}	f20	f21	CY _{dr}	CY _{dr} f ₁₉	
ASSOCIATED CARD									
M	M.CM _x								
0	.17	-.3449	-.220	0	0	0	.092	0	
.5	.19	-.3518	-.245	0	-.005	0	.092	.0092	
.7	.24	-.3736	-.292	.225	-.017	.012	.092	.019	
.9	.44	-.4085	-.305	.225	-.032	.018	.096	.031	
1.0	.77	-.4246	-.310	0	-.049	0	.095	.039	
1.05	1.25	-.4246	-.317	.075	-.068	.027	.080	.045	
1.10	1.49	-.4441	-.326	.275	-.098	.088	.079	.065	
1.15	1.27	-.4206	-.336	.440	-.109	.145	.083	.079	
1.20	0.92	-.4401	-.359	.750	-.118	.201	.083	.070	
1.40	0.19	-.4332	-.325	.750	-.147	.316	.053	.038	
1.70	0.16	-.4120	-.246	.473	-.110	.222	.096	.083	
2.00	0.16	-.3759	-.220	.440	-.122	.229	.056	.052	
2.50	0.16	-.3300	-.180	.238	-.190	.254	.029	.039	

AVRO AIRCRAFT LIMITED

TECHNICAL DEPT. (AIRFRAME)

AIRCRAFT Arrow Simulator

WEIGHT - - - 55,000 lb.

C. G. POSITION . .29c

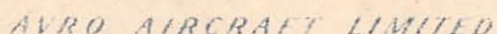
REPORT NO. 70/Sim./14

SHEET 2.4

DATE . . . D. J. Foster

PREPARED BY -

	1	2	3	4	5	6	7	8	9
Card No.	27	28	29	30	31	32			
Derivative Function	Cn _{βR}	Cn _{βα}	Cn _{δr}	Cn _{δra}	f22	Cn _{δαR}			
M									
0	.02584	-.0657	-.0412	.0286	0	-.0110			
.5	.02690	-.0657	-.0413	.0316	.11	-.0110			
.7	.02738	-.1410	-.0419	.0330	.26	-.0110			
.9	.02993	-.1770	-.0416	.0295	.40	-.0117			
1.0	.04099	-.2173	-.0404	.0198	.52	-.0135			
1.05	.05524	-.3071	-.0398	.0240	.61	-.0123			
1.10	.04822	-.1963	-.0399	.0300	.78	-.0113			
1.15	.03366	-.2197	-.0394	.0328	1.00	-.0118			
1.20	.03954	-.2268	-.0386	.0319	1.05	-.0122			
1.40	.03386	-.2346	-.0332	.0230	1.02	-.0074			
1.70	.01614	-.3116	-.0226	.0256	.98	-.0055			
2.00	.01073	-.1156	-.0178	.0230	1.25	-.0050			
2.50	.00516	-.0636	-.0173	.0252	1.71	-.0043			



TECHNICAL DEPT. (AIRFRAME)

REPORT NO. 70/Sim./14

SHEET 2.5

DATE . . . February 1958

AIRCRAFT Arrow Simulator

WEIGHT . . . 55,000 lb.

C. G. POSITION29c

PREPARED BY . D. J. Foster

Card No.	1	2	3	4	5	6	7	8	9
Derivative Function	Mach Followup	$Cn_{\delta \alpha}$	f_{23}	Cn_T	Cn_p		$Cl_{\beta R}$	$Cl_{\beta \alpha}$	
M									
0	0	.0425	0	-.107	-.0480		-.0150	-.550	
.5	0.50	.0412	.20	-.107	-.0480		-.0135	-.556	
.7	0.70	.0400	.366	-.107	-.0492		-.0100	-.561	
.9	0.90	.0570	.663	-.183	-.0780		-.0150	-.565	
1.0	1.00	.0850	.688	-.233	.1020		-.0280	-.575	
1.05	1.05	.0810	.792	-.181	.0855		-.0505	-.565	
1.10	1.10	.0785	.901	-.136	.0583		-.0515	-.765	
1.15	1.15	.0810	1.002	-.119	.0300		-.0450	-.730	
1.20	1.20	.0930	1.108	-.114	.0083		-.0645	-.765	
1.40	1.40	.0640	1.529	-.104	-.0160		-.0630	-.285	
1.70	1.70	.0470	2.368	-.099	-.0073		-.0725	-.115	
2.00	2.00	.0460	2.804	-.097	.0062		-.0575	-.195	
2.50	2.50	.0460	3.888	-.096	.0062		-.0530	-.350	

AVRO AIRCRAFT LIMITED

TECHNICAL DEPT. (AIRFRAME)

REPORT NO. 70/Sim./14

SHEET . . . 2.6

DATE . . . February 1958

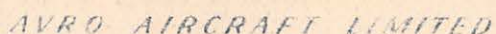
AIRCRAFT . . . Arrow Simulator

WEIGHT 55,000 lb.

C. G. POSITION .290

PREPARED BY - D. J. Foster

	1	2	3	4	5	6	7	8	9
Card No.	41	42	43	44	45	46	47	48	
Derivative Function	CL _{8r}	CL _{8r} ^{f24}	CL _{8a}	1	CL _{pR}	CL _p ^{f26}	Ch _{o,e}	Ch _{8e}	
ASSOCIATED CARD									
M					-M.CI _p	-M.CI _p ^{f26}			
0	.00748	.00337	-.0860	16.264	-.17	-.012	.0050	-.0115	
.5	.00808	.00374	-.0869	16.264	-.17	-.015	.0050	-.0115	
.7	.00877	.00491	-.0899	16.264	-.185	-.025	.002	-.0120	
.9	.00955	.00649	-.0970	16.476	-.238	-.064	-.002	-.0200	
1.0	.0100	.00720	-.0940	16.914	-.345	-.122	-.008	-.0329	
1.05	.01032	.00826	-.0888	17.355	-.425	-.166	.006	-.0333	
1.10	.01083	.01040	-.0825	18.336	-.495	-.223	.020	-.0326	
1.15	.01139	.01287	-.0755	17.865	-.445	-.218	.017	-.0315	
1.20	.01137	.01330	-.0688	17.934	-.400	-.205	.032	-.0305	
1.40	.00927	.01130	-.0440	19.514	-.352	-.228	.042	-.0262	
1.70	.00735	.00985	-.0340	18.935	-.350	-.274	.038	-.0201	
2.00	.00601	.00962	-.02640	18.974	-.350	-.320	.027	-.0153	
2.50	.00393	.00668	-.0135	18.974	-.350	-.372	.016	-.0107	



TECHNICAL DEPT. (AIRFRAME)

REPORT NO. - 70/Sim./14

SHEET . . . 2.7

DATE . . . Feb. 1958

AIRCRAFT Arrow Simulator

WEIGHT 55,000 lb.

C. G. POSITION .29c

PREPARED BY - D. J. Foster

	1	2	3	4	5	6	7	8	9
Card No.	49	50	51	52	53	54	55	56	
Derivative Function	$Ch_{\alpha, e}$	$Ch_{\alpha, a}$	$Ch_{\delta a}$	$Ch_{\alpha, a}$	$Ch_{\beta, r}$	$Ch_{\delta r}$	M	M	
M									
0	-.0028	-.003	-.0072	-.0049	.0025	-.0055	0	0	
.5	-.0028	-.003	-.0072	-.0049	.0025	-.0055	.50	.50	
.7	-.0031	-.002	-.0080	-.0058	.0025	-.0060	.70	.70	
.9	-.0028	-.003	-.0099	-.0088	.00245	-.0075	.90	.90	
1.0	-.0030	-.012	-.0178	-.0151	.00284	-.0088	1.00	1.00	
1.05	-.0120	.009	-.0230	-.0182	.00431	-.0098	1.05	1.05	
1.10	-.0130	.024	-.0194	-.0156	.00848	-.0104	1.10	1.10	
1.15	-.0136	.035	-.0194	-.0215	.00536	-.0104	1.15	1.15	
1.20	-.0128	.048	-.0185	-.0207	.00648	-.0100	1.20	1.20	
1.40	-.0134	.027	-.0179	-.0206	.00572	-.0104	1.40	1.40	
1.70	-.0132	.020	-.0176	-.0204	.00152	-.0160	1.70	1.70	
2.00	-.0124	.005	-.0154	-.0165	.00277	-.0090	2.00	2.00	
2.50	-.0116	-.010	-.0132	-.0125	.00380	-.0075	2.50	2.50	

AVRO AIRCRAFT LIMITED

TECHNICAL DEPT. (AIRFRAME)

REPORT NO. 70/Sim./14

SHEET 2.8

DATE . . . February 1958

AIRCRAFT Arrow Simulator

WEIGHT " " 55,000 lb.

C. G. POSITION . 29c

PREPARED BY - D. J. Foster

[illegible]

AVRO AIRCRAFT LIMITED

TECHNICAL DEPT. (AIRFRAME)

AIRCRAFT Arrow Simulator

WEIGHT . . . 55,000 lb.

C. G. POSITION .29c

REPORT NO. . 70/Sim./14

SHEET . . . 2.9

DATE . . . February 1958

PREPARED BY D. J. Foster

Card No.	1	2	3	4	5	6	7	8	9
Function	Altitude Pot	g_1	g_3	g_9	g_{10}	g_{19}	g_{20}	g_{22}	
ASSOCIATED MACH. CARD		CL_α	CL_{be}	CM_o	CM_{be}	CY_{br}	$(f_{20} + f_{21})$	CM_{br}	
ALTITUDE									
0		1.000	1.000	1.00	1.00	1.00	1.00	1.00	
5,000'		.905	.907	.381	.856	.884	.855	.678	
10,000'		.805	.814	.759	.725	.786	.738	.530	
15,000'		.710	.722	.647	.615	.697	.647	.462	
20,000'		.616	.632	.544	.515	.611	.575	.445	
25,000'		.535	.546	.458	.425	.534	.499	.398	
30,000'		.465	.462	.385	.347	.459	.420	.316	
35,000'		.396	.388	.319	.281	.388	.351	.256	
40,000'		.322	.325	.260	.227	.320	.298	.223	
50,000'		.212	.218	.178	.145	.214	.209	.151	
60,000'		.135	.142	.118	.083	.136	.136	.102	
70,000'		.070	.089	.072	.035	.070	.070	.072	
80,000'		.025	.046	.034	.009	.025	.025	.047	

AVRO AIRCRAFT LIMITED

TECHNICAL DEPT. (AIRFRAME)

AIRCRAFT - Arrow Simulator

WEIGHT 55,000 lb.

C. G. POSITION 29c

REPORT NO. 70/Sim./14

SHEET - - 2.10

DATE February 1958

PREPARED BY . D. J. Foster

[illegible]

AVRO AIRCRAFT LIMITED

TECHNICAL DEPT. (AIRFRAME)

AIRCRAFT Arrow Simulator

WEIGHT . . . 55,000 lb.

C. G. POSITION . 29c

REPORT NO. 70/Sim./14

SHEET 2.11

DATE - February 1958

PREPARED BY - D. J. Foster

	1	2	3	4	5	6	7	8	9
Card No.	81	82	83	84	85	86	87	88	
Function	E35	E36		a		$\frac{ap}{ap_0}$	$\frac{ap}{ap_0}$	$\frac{ap}{ap_0}$	
REMARKS	AB Thrust	A/B Thrust				input p	input q	input r	
ALTITUDE									
0	15,501.	-10,149		1/1,116		1.00	1.00	1.00	
5,000'	24,400.	-11,290		1/1097		.8473	.8473	.8473	
10,000'	31,700.	-13,500		1/1077		.7122	.7122	.7122	
15,000'	38,018.	-14,757		1/1057		.5957	.5957	.5957	
20,000'	42,069.	-14,631		1/1037		.4952	.4952	.4952	
25,000'	63,761.	-19,853		1/1017		.4081	.4081	.4081	
30,000'	72,142.	-20,132		1/995		.3336	.3336	.3336	
35,000'	56,358.	-15,115		1/972		.2665	.2665	.2665	
40,000'	53,763.	-14,334		1/972		.2134	.2134	.2134	
50,000'	18,294.	-5242.1		1/972		.1324	.1324	.1324	
60,000'	12,040.	-3158		1/972		.0819	.0819	.0819	
70,000'	6901.8	-1810.3		1/972		.0505	.0505	.0505	
80,000'	3891.8	-1020.8		1/972		.0300	.0300	.0300	

AVRO AIRCRAFT LIMITED

TECHNICAL DEPT. (AIRFRAME)

REPORT NO. . 70/Sim./14

SHEET . . . 2.12

DATE . . . February 1958

PREPARED BY - D. J. Foster

AIRCRAFT Arrow Simulator

WEIGHT . . . 55,000 lb.

C. G. POSITION $.29\bar{c}$ [illegible]



AVRO AIRCRAFT LIMITED
MALTON - ONTARIO

TECHNICAL DEPARTMENT

REPORT No. 70/Sim./14

SHEET No. 3.i.

AIRCRAFT:

Arrow Flight
Simulator

PREPARED BY

DATE

D. J. Foster

Feb. 1958

CHECKED BY

DATE

List of Circuit Diagrams

Note:-

Since the circuit diagrams were drawn, there have been a number of minor modifications made, but these do not invalidate the general schemes outlined for the mechanization of the equations.

Sheet No.	Title
3.1	Lift Equation
3.2	Drag Equation
3.3	Sideslip Equation
3.4	Pitch Equation
3.5	Roll Equation
3.6	Yaw Equation
3.7	Altitude Equation
3.8	Thrust Computation
3.9	Reeves Servo Utilisation
3.10	M^2/p_0 Servo Utilisation
3.11	High incidence effects on pitching moment coefficient
3.12	High incidence effects on sideslip derivatives
3.13	Ground Reaction Circuit
3.14	Ground Effect on Pitching moment coefficient
3.15	Undercarriage switching circuits
3.16	Rudder rate limiting circuit (due to hinge moments)
3.17	Function Generator Utilisation
3.18	Euler angle resolution circuit
3.19	Rate of turn and compass heading
3.20	Aircraft display circuit
3.21	Fixed gain pitch damper circuit
3.22	Fixed gain roll damper circuit
3.23	Fixed gain yaw damper circuit
3.24	Variable gain yaw damper circuit
3.25	Ay monitor circuit



AVRO AIRCRAFT LIMITED
MALTON ONTARIO

TECHNICAL DEPARTMENT

REPORT NO _____

SHEET NO _____

AIRCRAFT:

Arrow Simulator

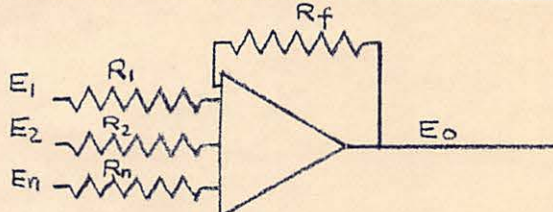
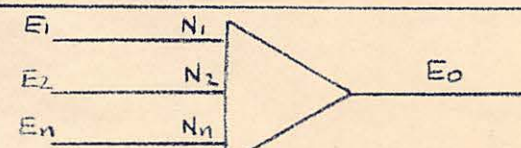
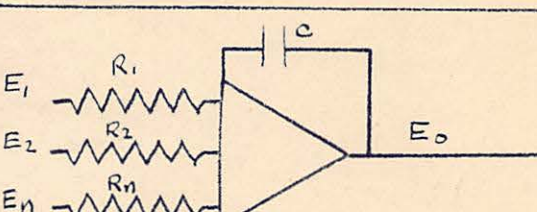
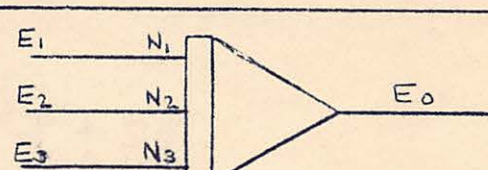
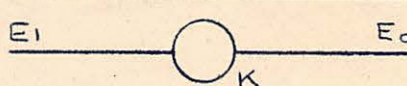
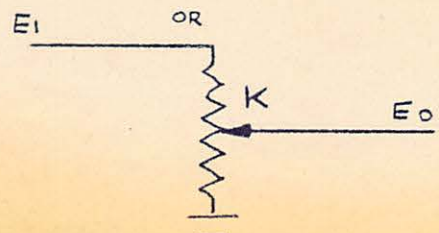
PREPARED BY _____

DATE _____

CHECKED BY _____

DATE _____

EXPLANATION OF SYMBOLS USED IN CIRCUIT DIAGRAMS

SYMBOL	MEANING
	High Gain Amplifier. $E_o = 10^7 \frac{E_1}{R_1}$
	Summing amplifier. Adds together several inputs and multiplies by a constant. $E_o = -R_f \left(\frac{E_1}{R_1} + \frac{E_2}{R_2} + \dots + \frac{E_n}{R_n} \right)$
	Same as above $E_o = -(N_1 E_1 + N_2 E_2 + \dots + N_n E_n)$
	Integrating amplifier. Adds together several inputs and integrates them w.r. to time $E_o = -\frac{1}{C} \int \left(\frac{E_1}{R_1} + \frac{E_2}{R_2} + \frac{E_n}{R_n} \right) dt$
	Same as above $-E_o = \int (N_1 E_1 + N_2 E_2 + N_3 E_3 \dots) dt$
 OR 	Potentiometer $E_o = K \cdot E_1 \quad 0 < K < 1$



AVRO AIRCRAFT LIMITED
MALTON - ONTARIO

TECHNICAL DEPARTMENT

REPORT NO. _____

SHEET NO. _____

AIRCRAFT:

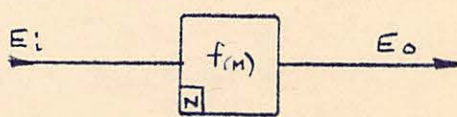
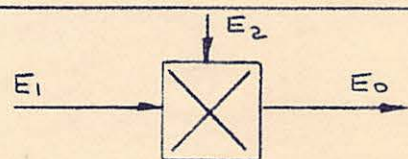
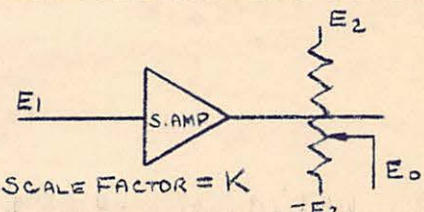
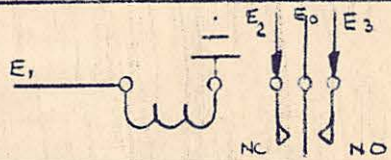
Arrow Simulator

PREPARED BY _____

DATE _____

CHECKED BY _____

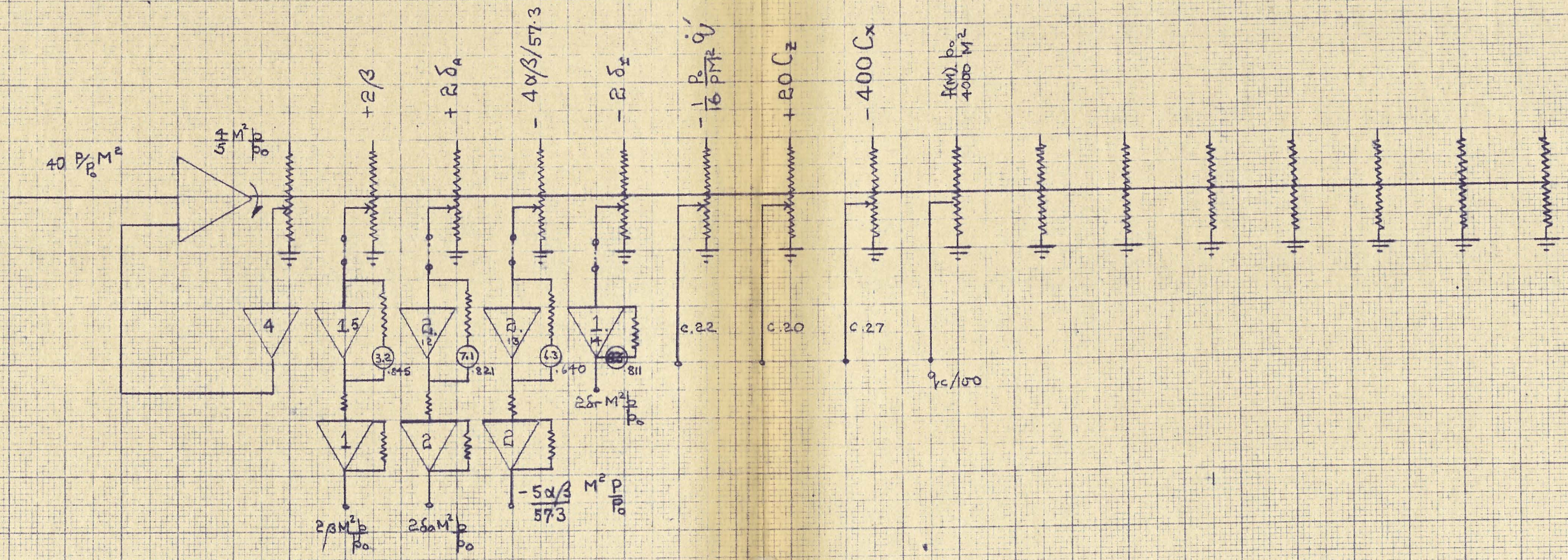
DATE _____

SYMBOL	MEANING
	Tapped potentiometer with wiper driven off servo shaft. $E_o = E_i \cdot f(M)$ N denotes the function number.
	Multiplier $E_o = E_1 \cdot E_2 \div K$ (sometimes a servo multiplier, sometimes an electronic multiplier)
 SCALE FACTOR = K	Servo Multiplier $E_o = K \cdot E_1 \cdot E_2$
	Relay $E_o = E_2, E_1 \leq 0$ $E_o = E_3, E_1 \geq 0$
	Diode
	Resistor
	Ground

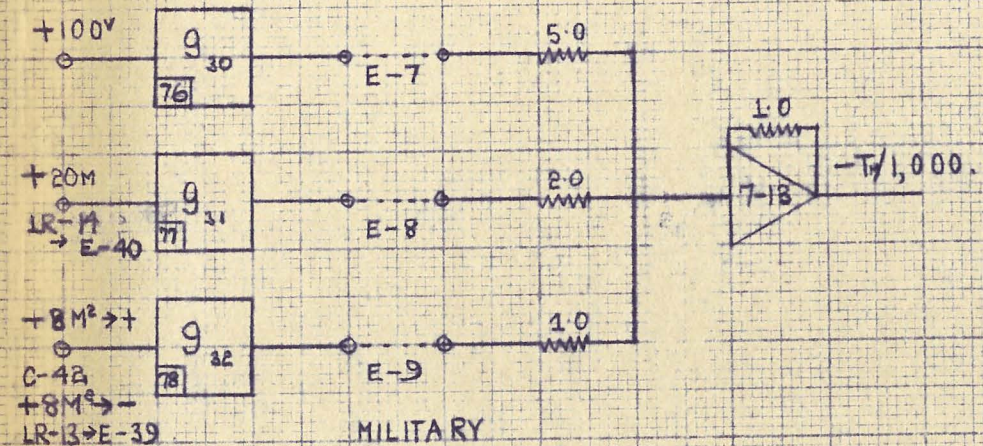
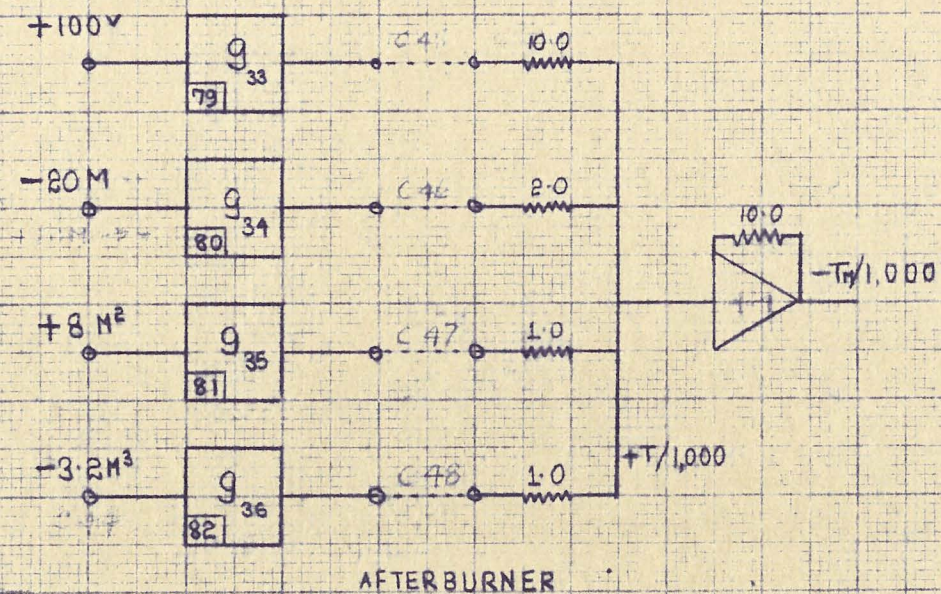
483-2

10 X 10 TO THE 1/2 INCH 359-11L KEUFFEL & ESSER CO. MADE IN U.S.A.

M²p/p₀ SERVO UTILISATION.

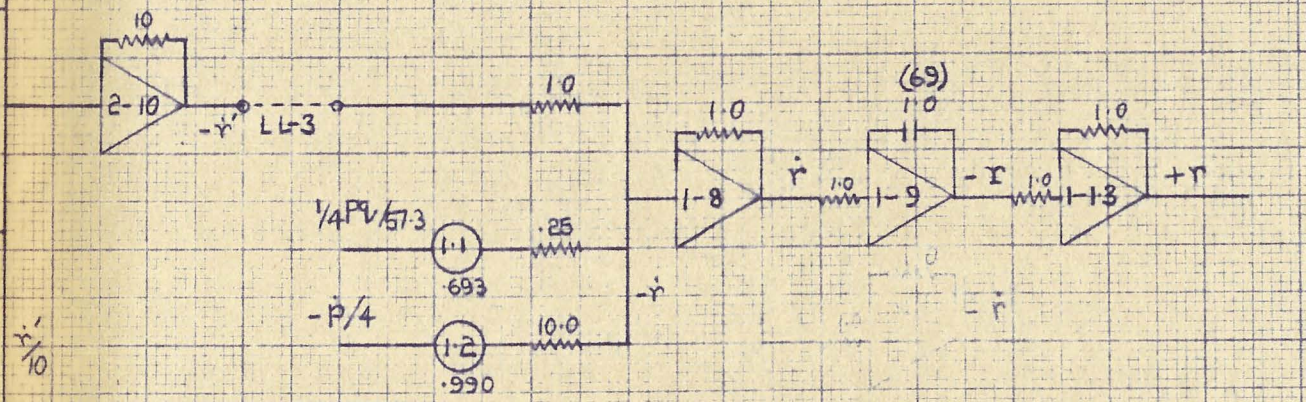
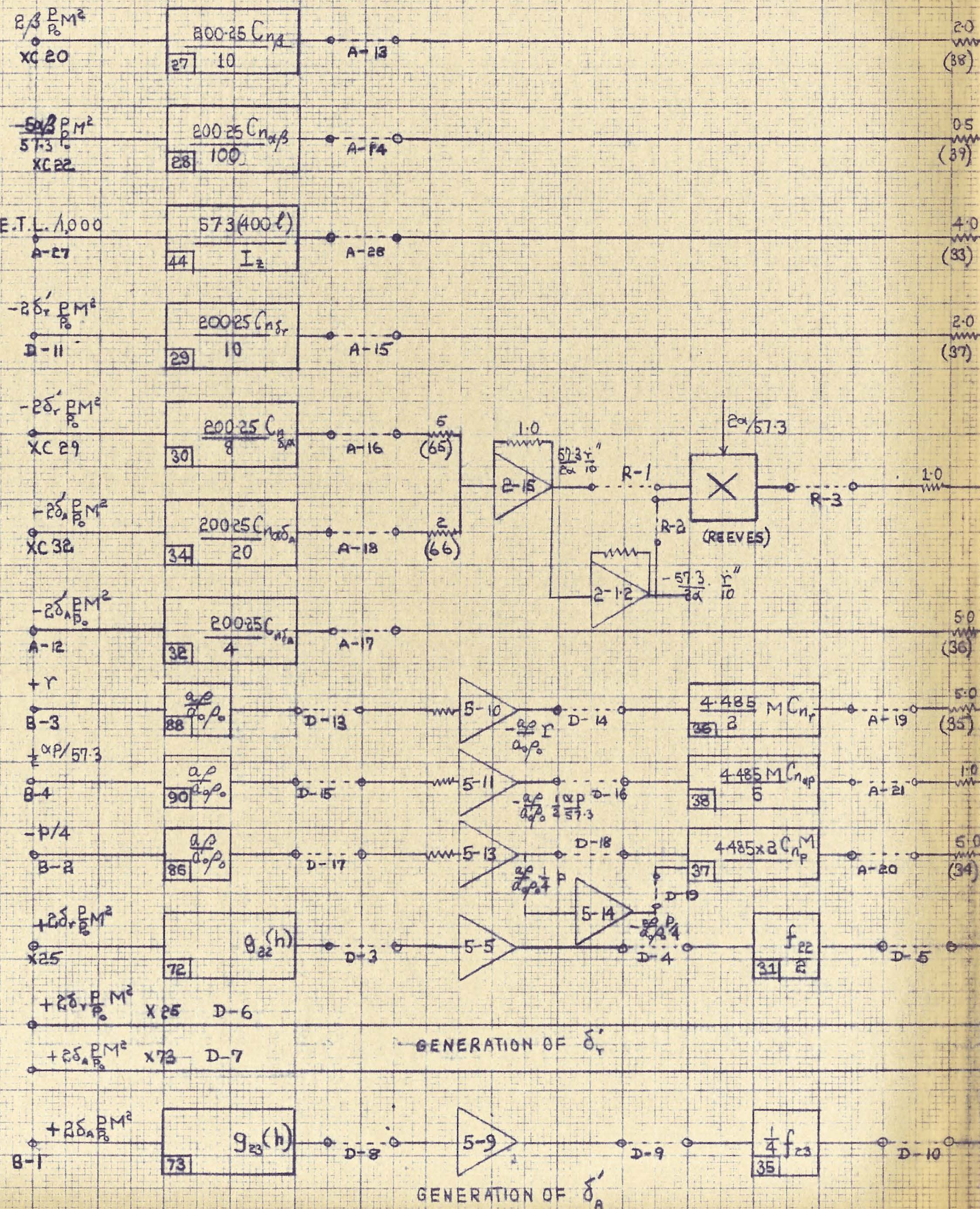


THRUST COMPUTATION

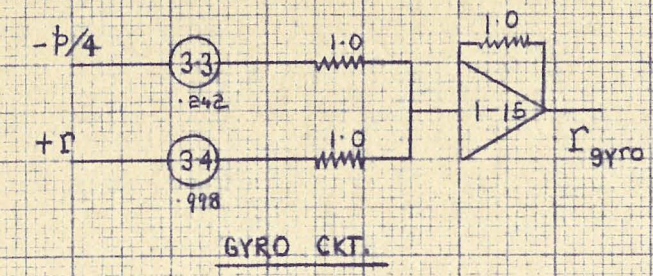


YAW EQUATION

$$\dot{r} = \frac{I_{xz}}{I_z} \dot{p} + \frac{I_x - I_y}{I_z} \frac{pq}{57.3} + \frac{57.3}{I_z} \sum N$$



NOTES: $\frac{S P_0 Y b}{2 I_z} = 200.25$
 $\frac{S b^2 a_0 p_0}{4 I_z} = 4.485$

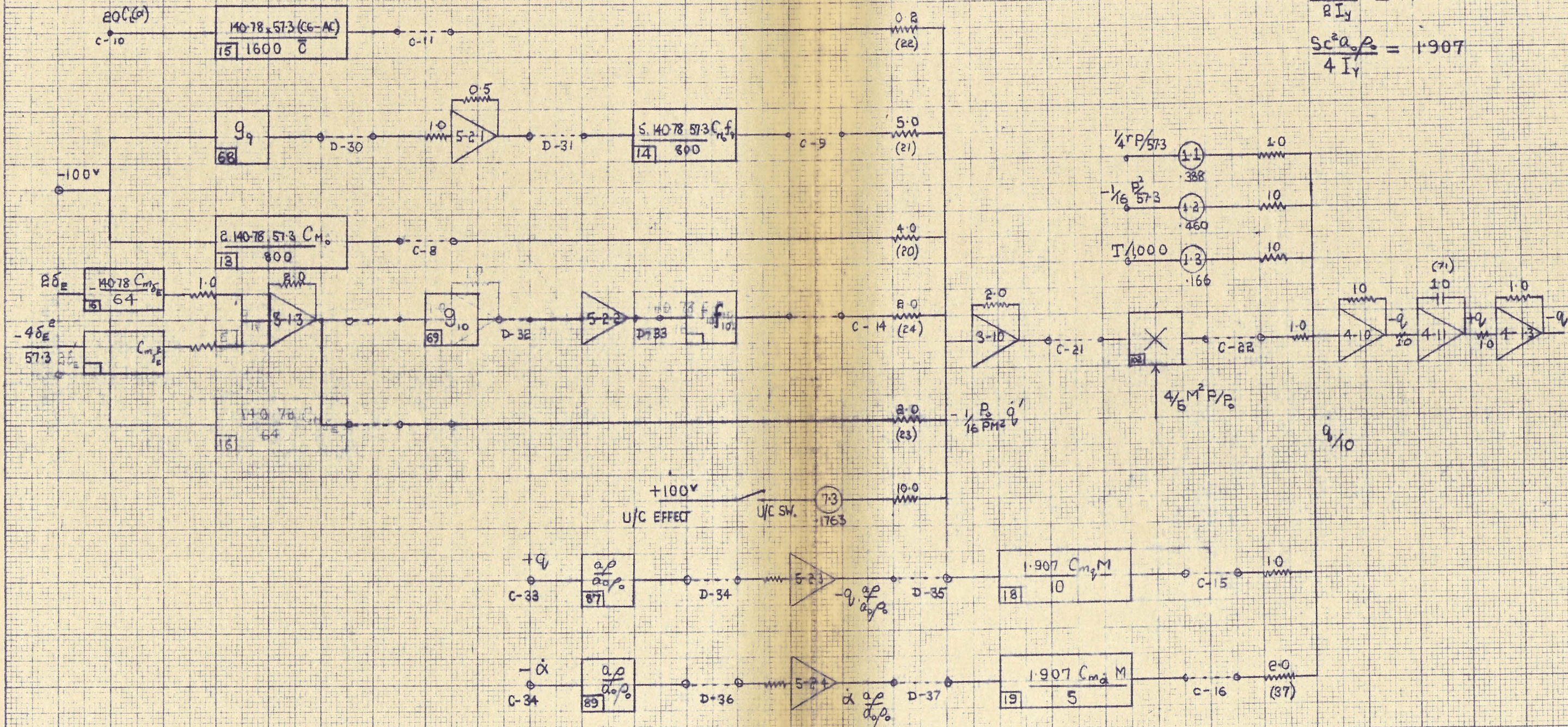


PITCH EQUATION

$$\dot{v} = \frac{I_z - I_x}{I_y} \frac{r p}{57.3} - \frac{I_{xz}}{I_y} \frac{p^2}{57.3} + \frac{57.3 e T}{I_y} + \frac{57.3 \sum M}{I_y}$$

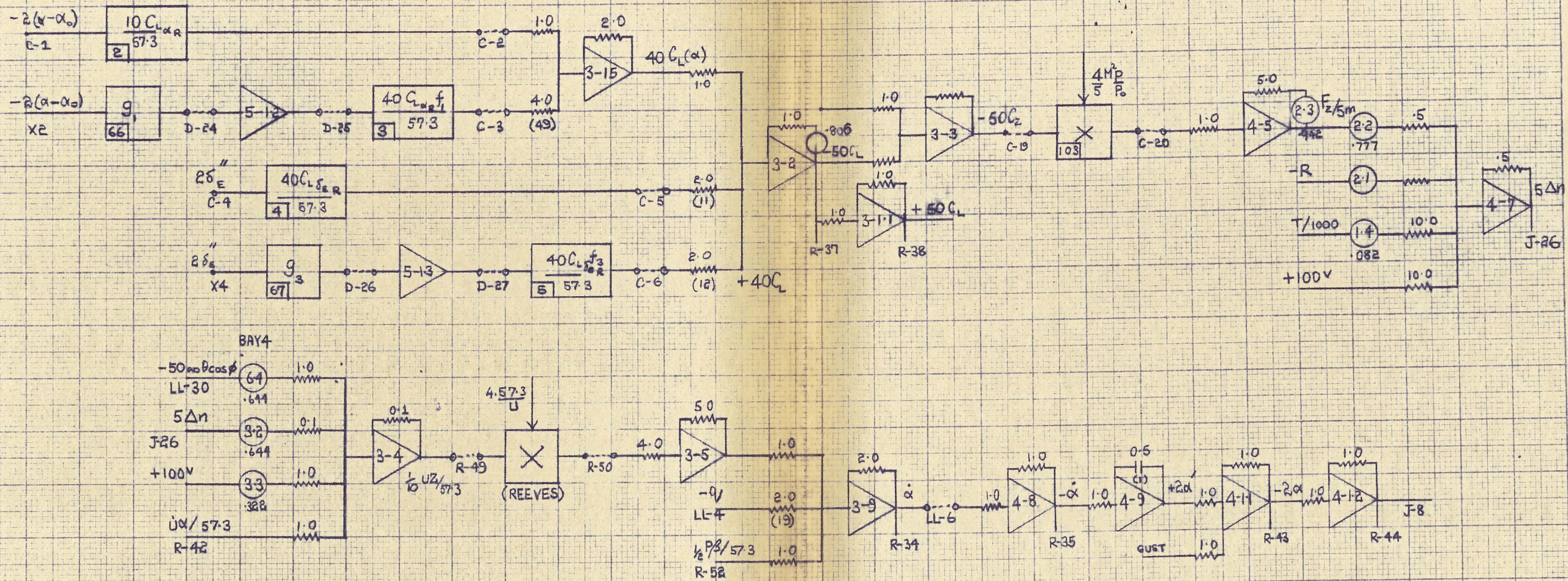
NOTE :- $\frac{S_p Y_c}{R I_y} = 140.70$

$$\frac{S c^2 a_p p}{4 I_y} = 1.907$$

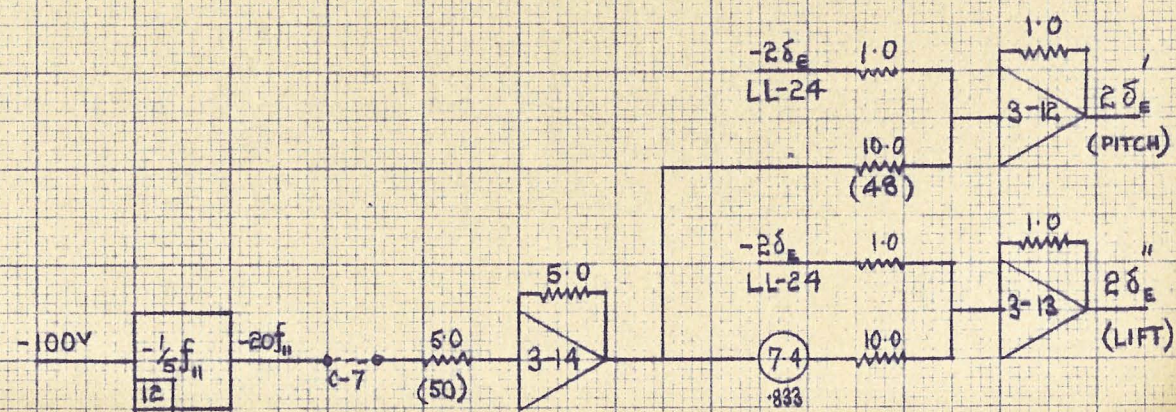


LIFT EQUATION

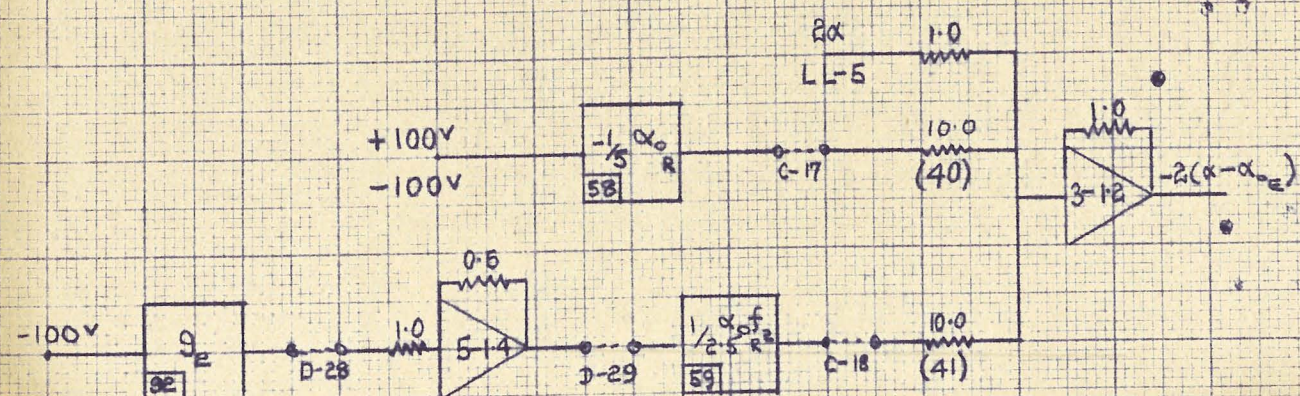
$$\dot{\alpha} = -\frac{P\phi}{57.3} + q_y + \frac{57.3}{U} \left[(g \cos \theta \cos \phi) - \dot{\alpha} + \sum F_z / m \right] \quad \Delta n = -\sum F_z / mg - 1$$



AILERON TRIM - EQUIVALENT ELEVATOR CKT.



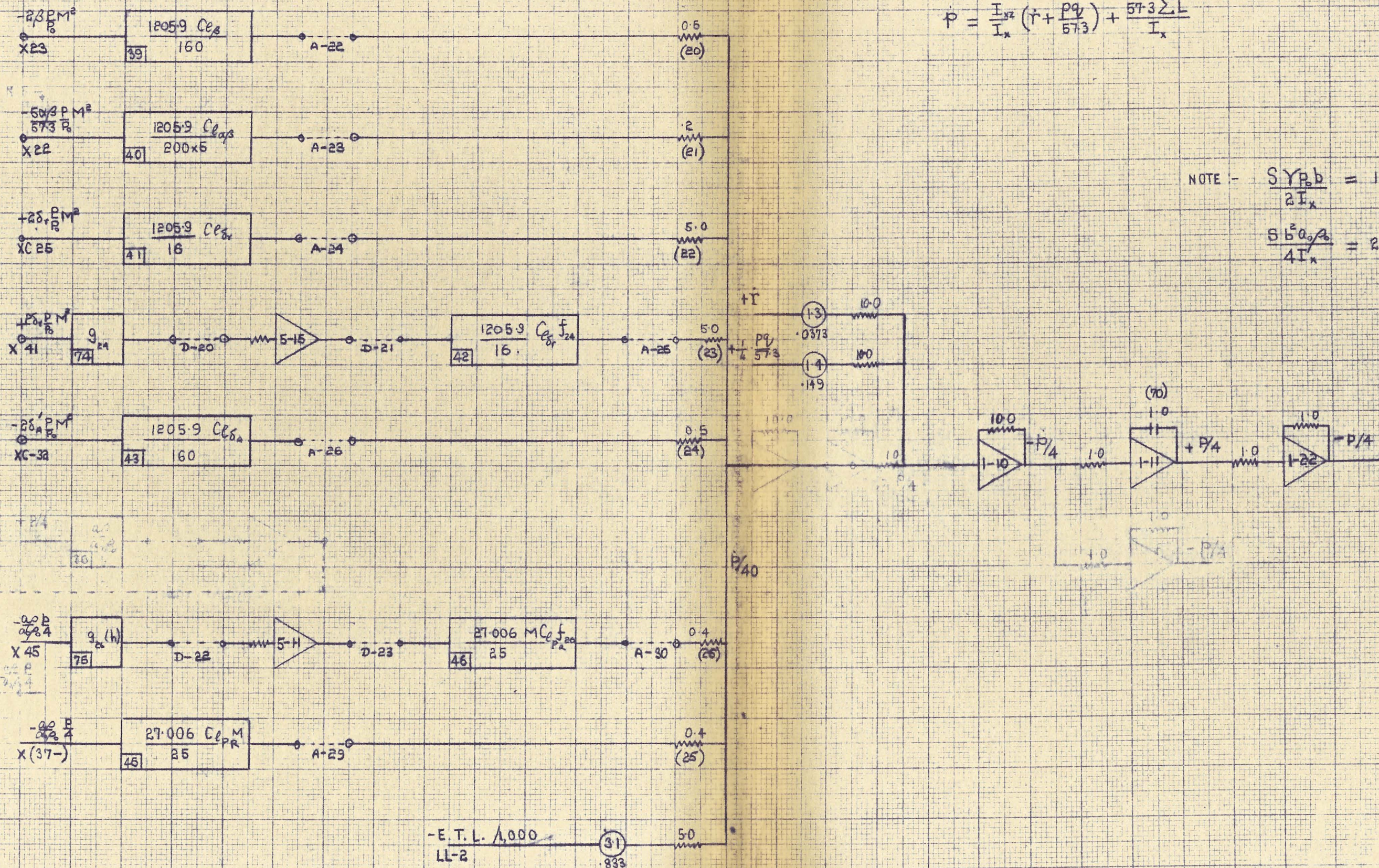
Q. CKT.



ROLL EQUATION

$$p = \frac{I_{xz}}{I_x} \left(r + \frac{pq}{57.3} \right) + \frac{57.3 \sum L}{I_x}$$

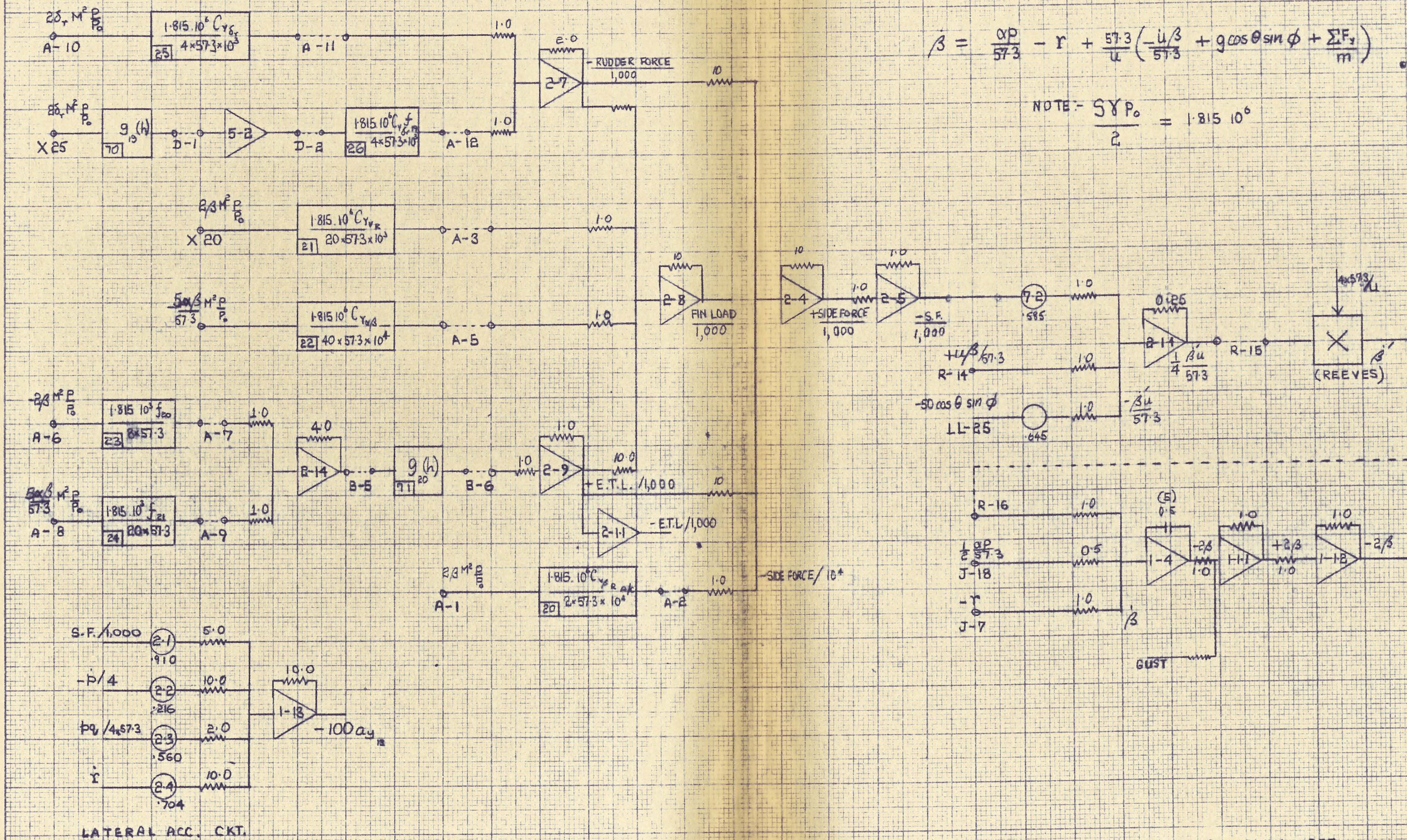
NOTE - $\frac{SY_{P,b}}{2I_x} = 1205.9$

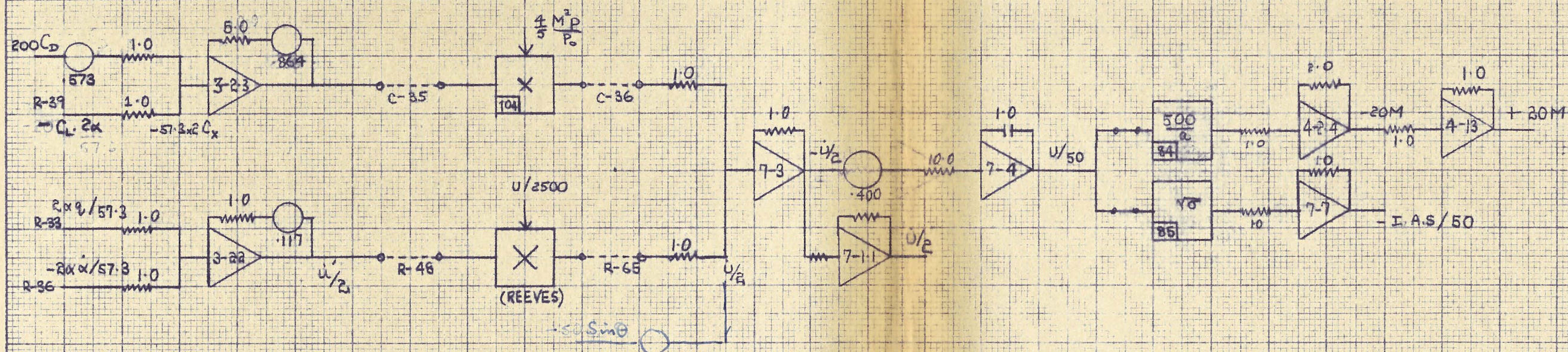
$$\frac{56^2 \times 0.9}{4 \Gamma} = 27.006$$


SIDSLIP EQUATION

$$\beta = \frac{\alpha p}{57.3} - r + \frac{57.3}{u} \left(\frac{-u}{57.3} + g \cos \theta \sin \phi + \frac{\sum F_y}{m} \right)$$

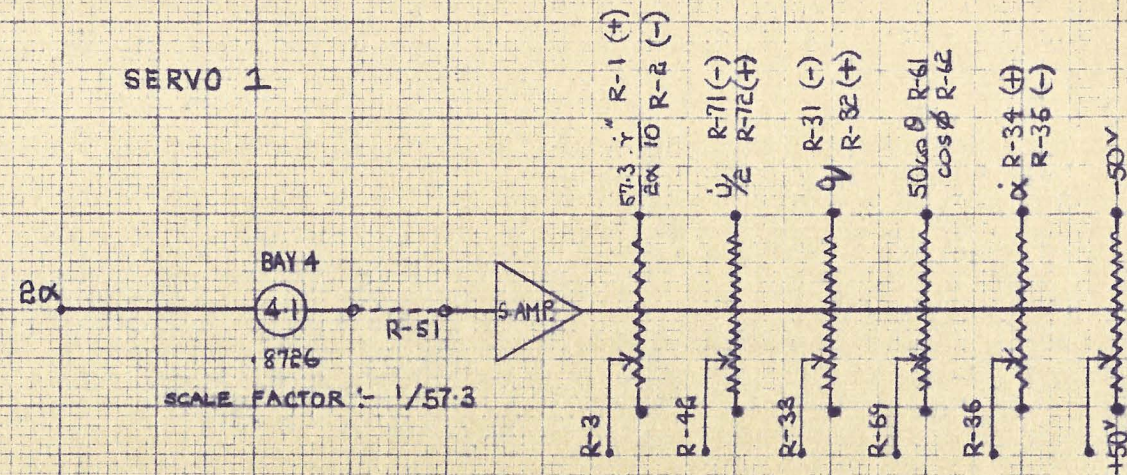
NOTE: $\frac{57.3}{2} = 1.815 \times 10^6$



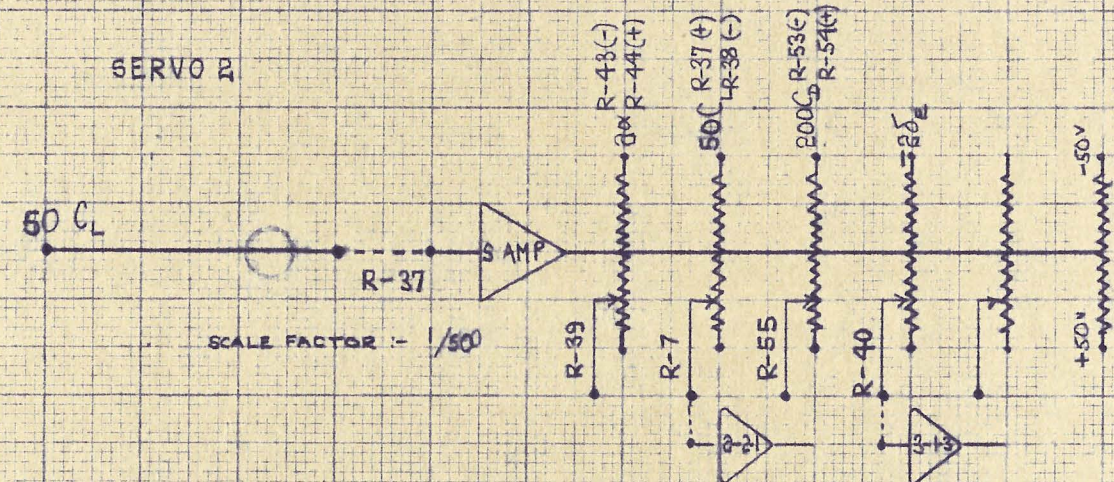
$$\dot{U} = \frac{U\alpha}{57.3^2} (-Q + \alpha) - \frac{g\theta}{57.3} - \frac{R\theta}{m \cdot 57.3} - \frac{T \cos i}{m} + \Sigma F_x / m.$$


REEVES SERVOS

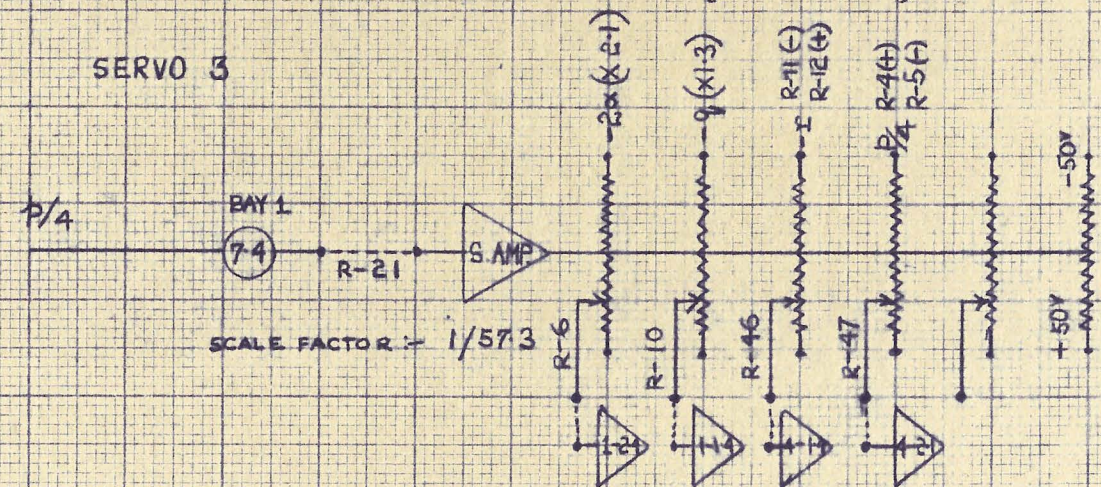
SERVO 1



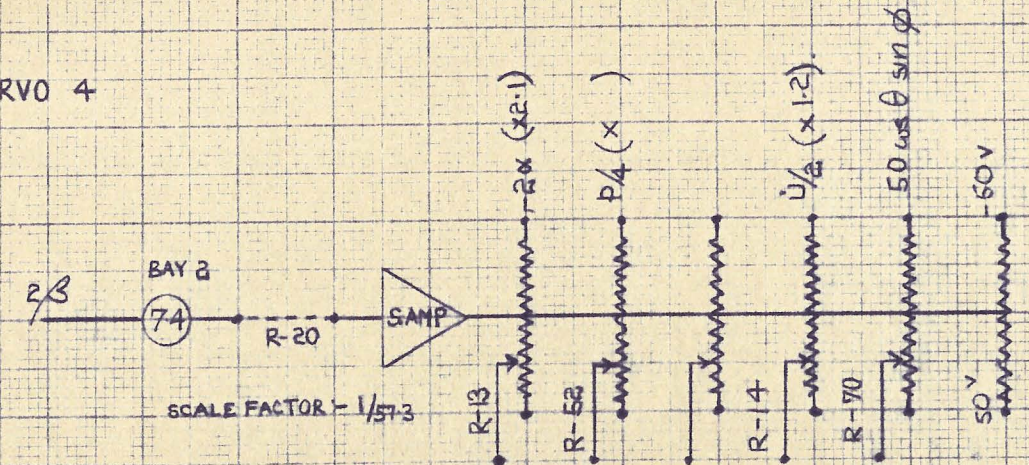
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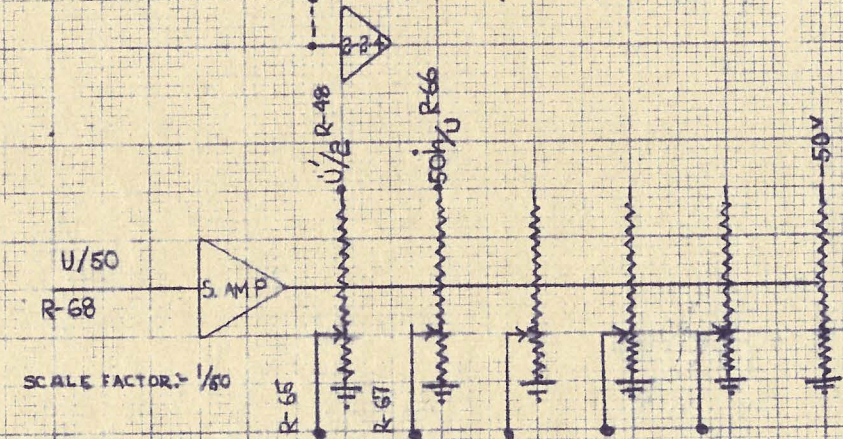
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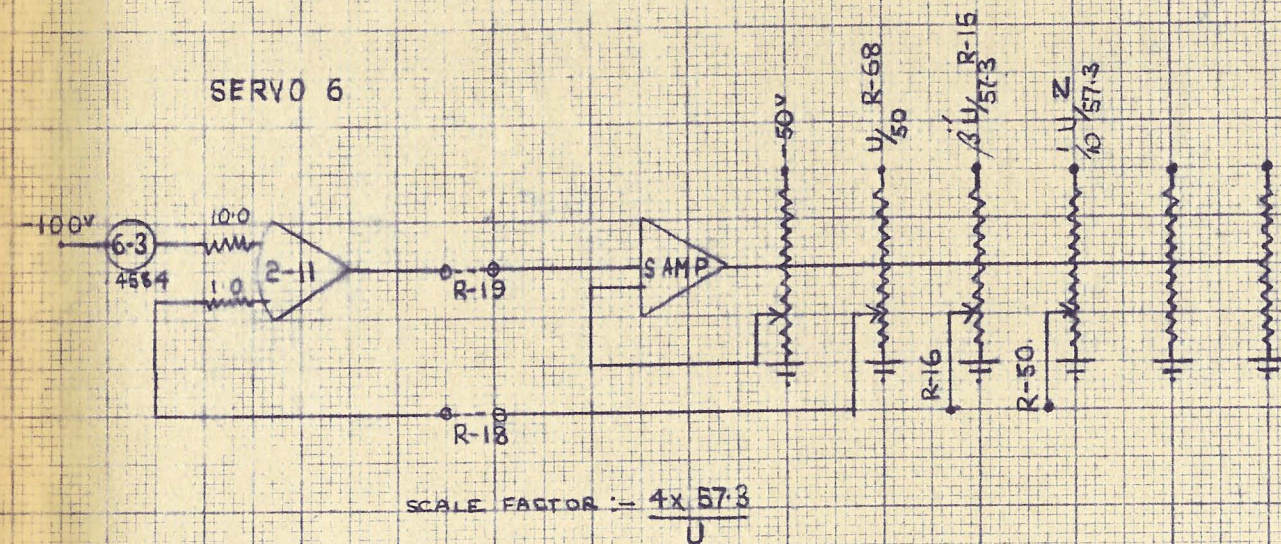
SERVO 4



SERVO 5

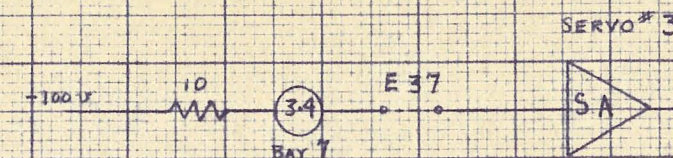
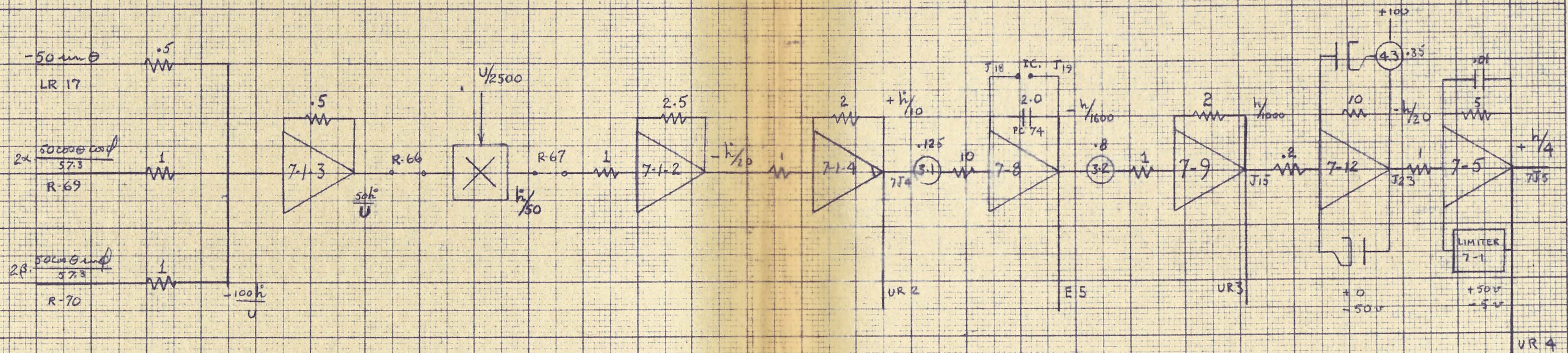


SERVO 6

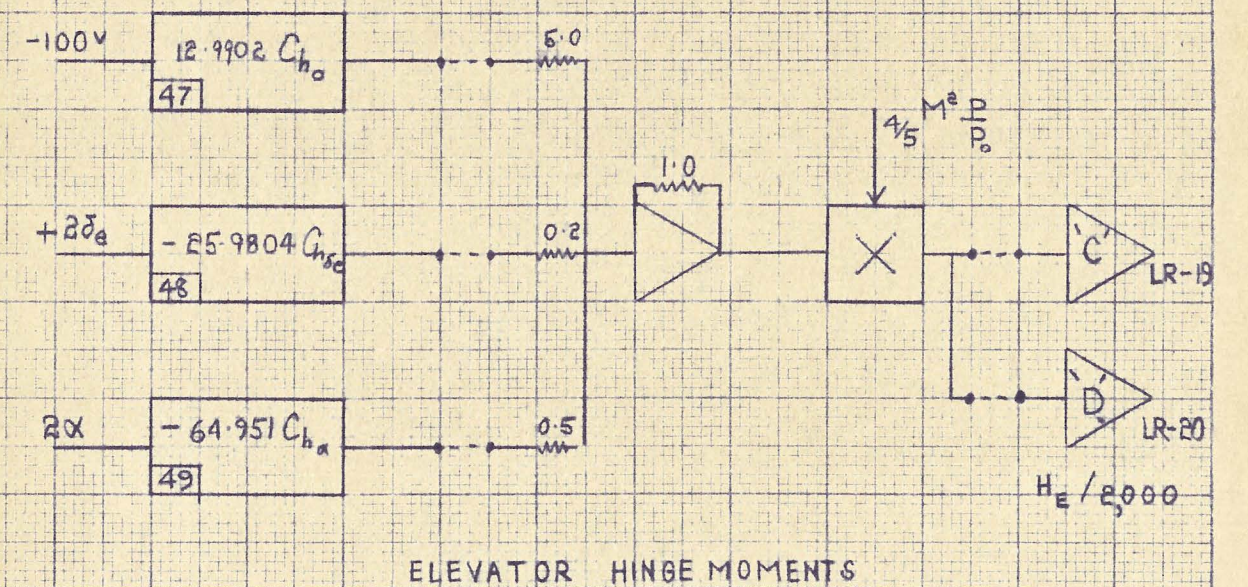
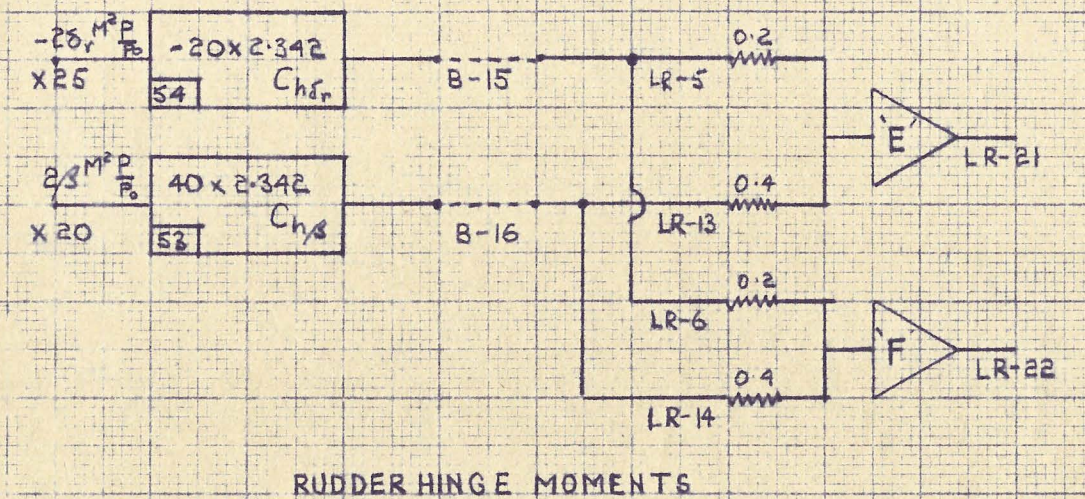
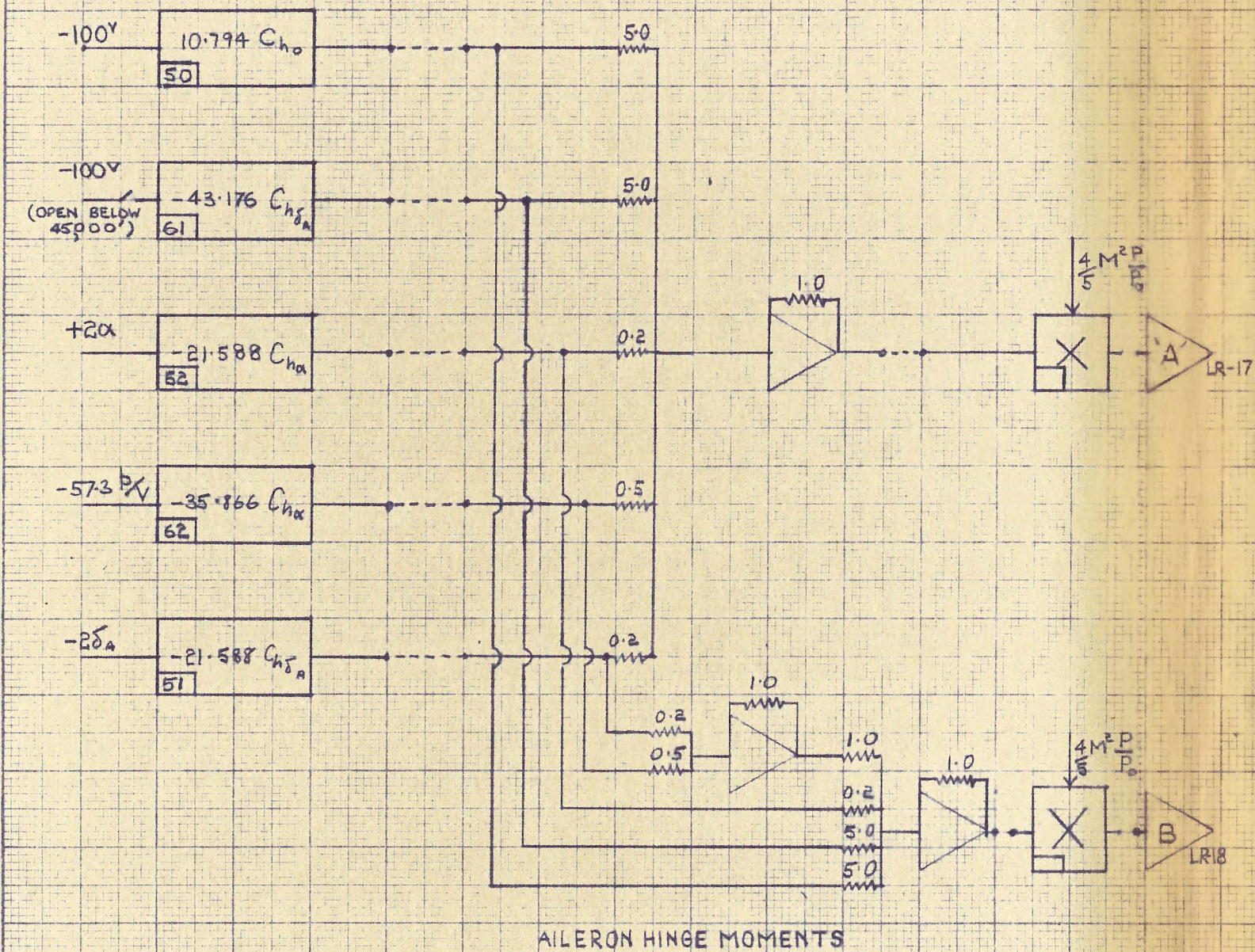


ALTITUDE EQUATION

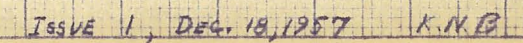
$$h_i = -U \{ \alpha \cos \theta \cos \phi + \beta \cos \theta \sin \phi - \sin \theta \}$$



FUNCTION GENERATOR.



K₁₇ 10 X 10 TO THE 1/2 INCH
KEUFFEL & ESSER CO.
359-11 L
MADE IN U.S.A.



TECHNICAL DEPARTMENT

AIRCRAFT:

CRAFT C-105
ROLL DAMPER

REPORT NO.

SHEET NO

PREPARED BY

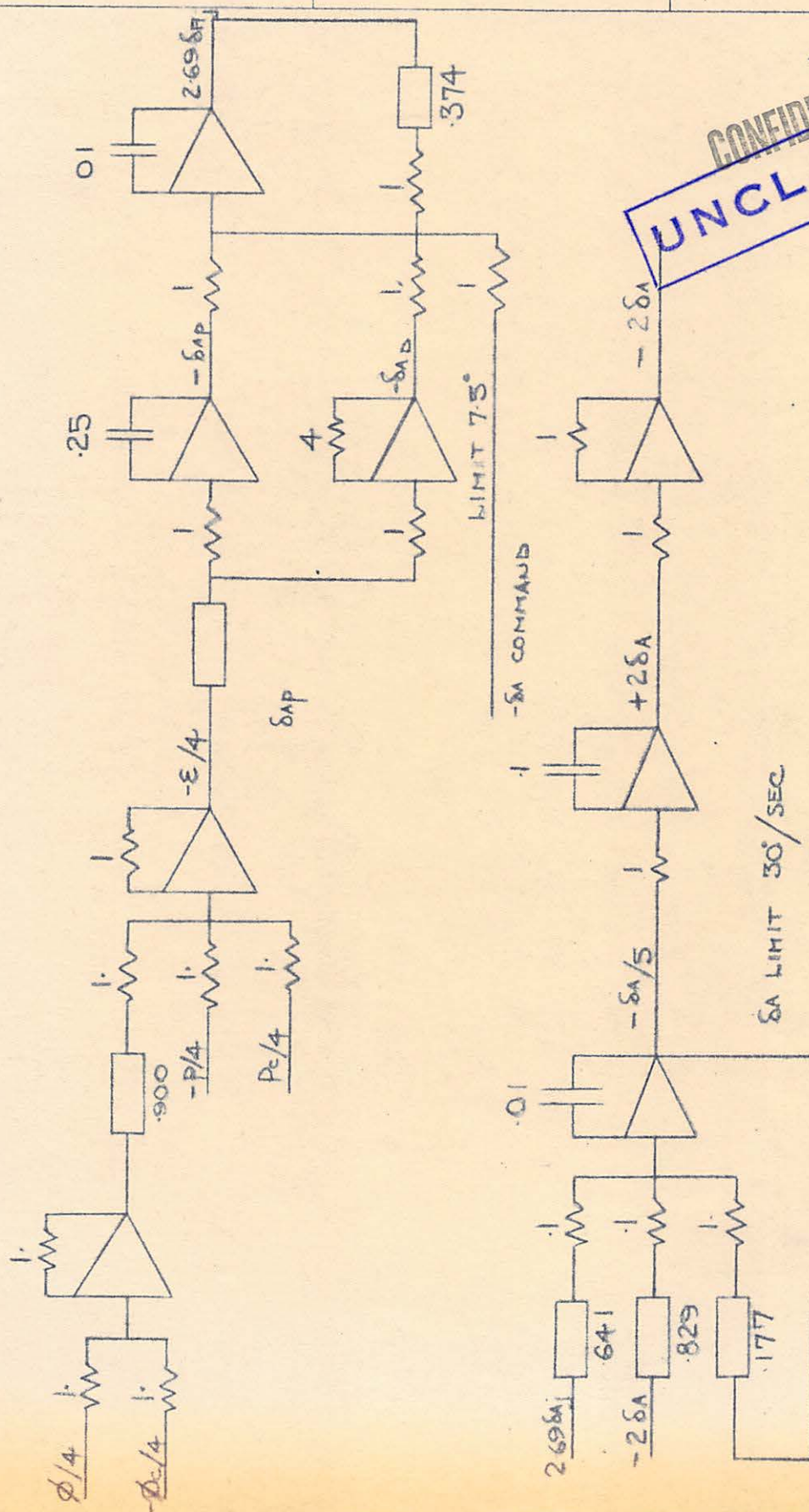
DATE _____

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 AVRO AIRCRAFT LIMITED
 MALTON, ONTARIO

TECHNICAL DEPARTMENT

AIRCRAFT:

C-105

RUDDER CONTROL

CIRCUIT

REPORT NO.

SHEET NO.

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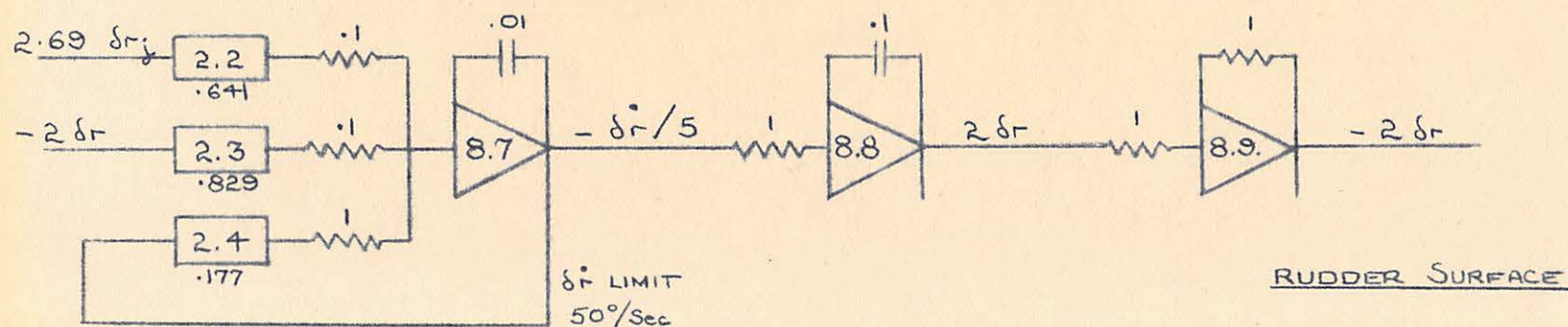
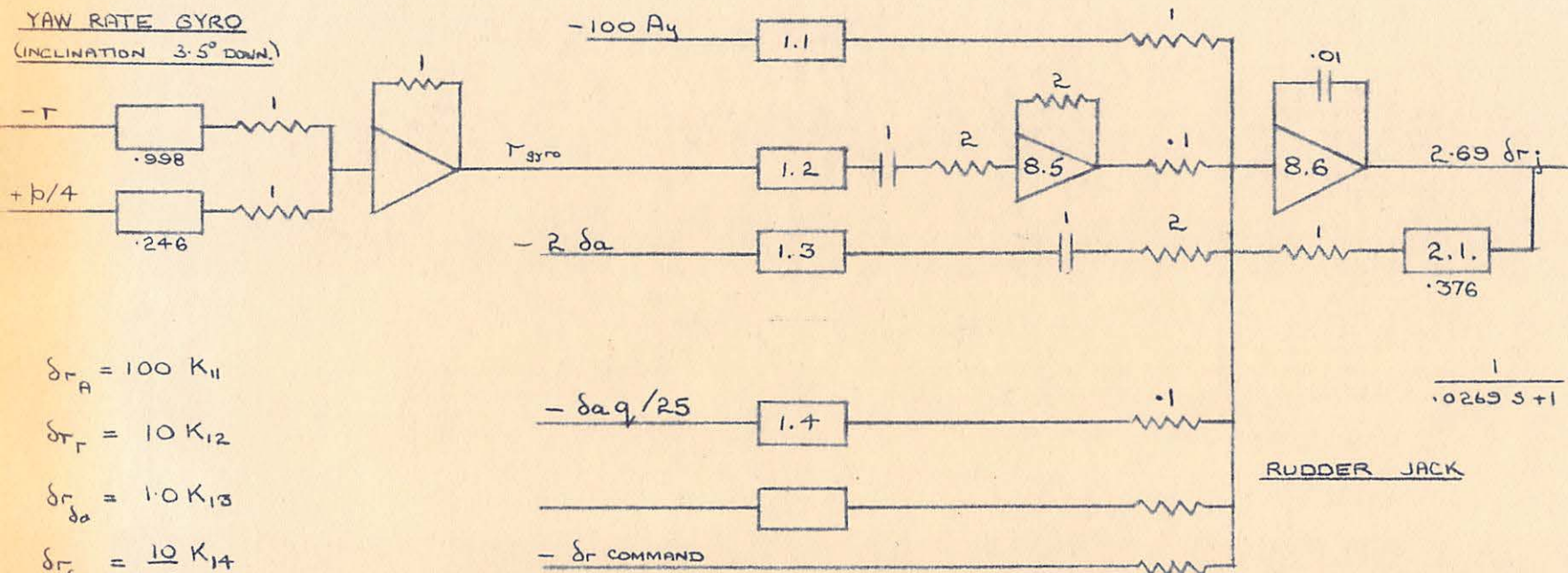
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TRACED, D. V. FOSTER

AUG 30 1957

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DATE

 YAW RATE GYRO
 (INCLINATION 3.5° DOWN.)




AVRO AIRCRAFT LIMITED
MALTON - ONTARIO

TECHNICAL DEPARTMENT

AIRCRAFT:

C-105

PITCH DAMPER

REPORT NO. _____

SHEET NO. _____

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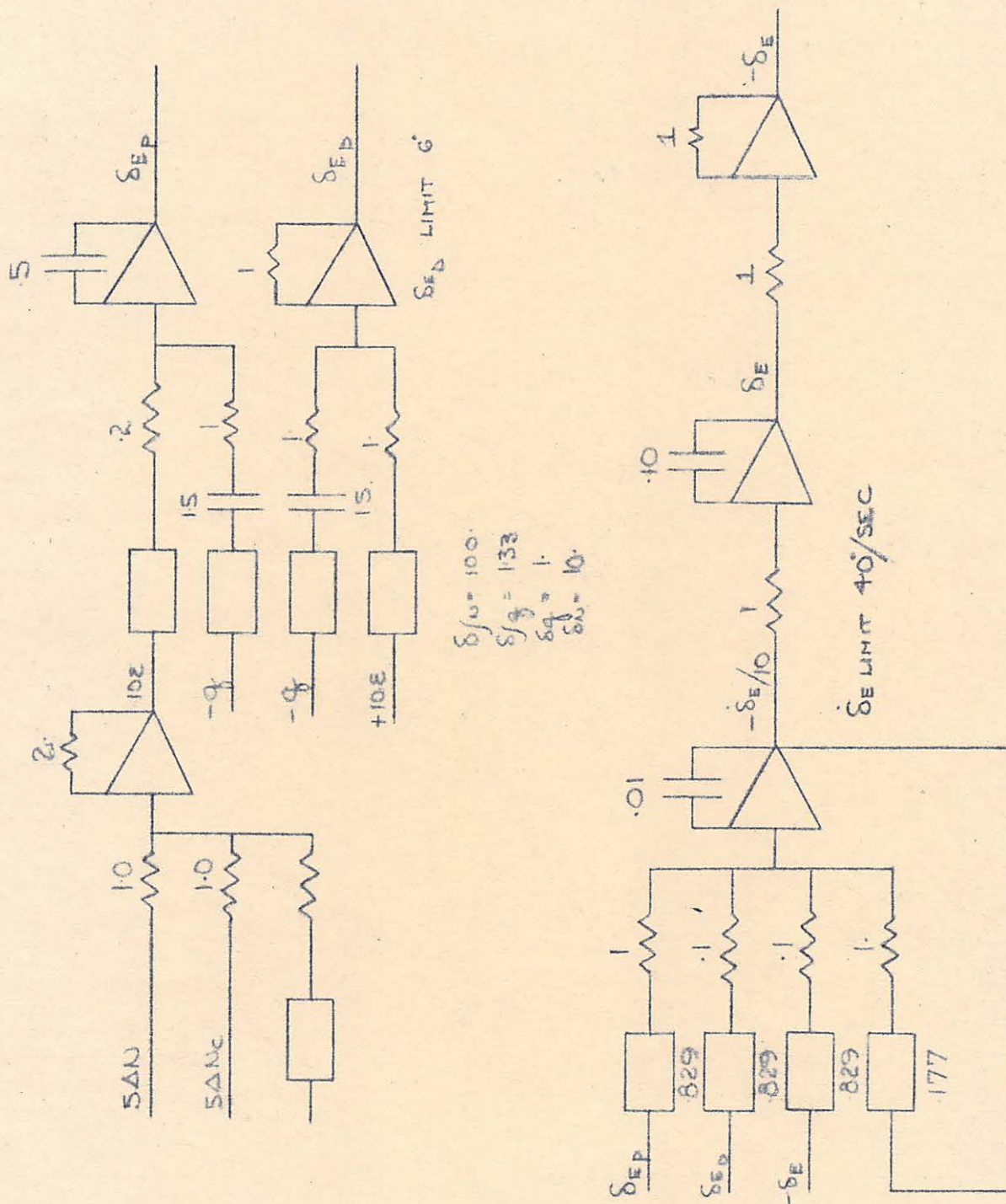
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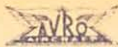
N.W.

AUG 30, 1957

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DATE





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TECHNICAL DEPARTMENT

REPORT NO. _____

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AIRCRAFT

C-105

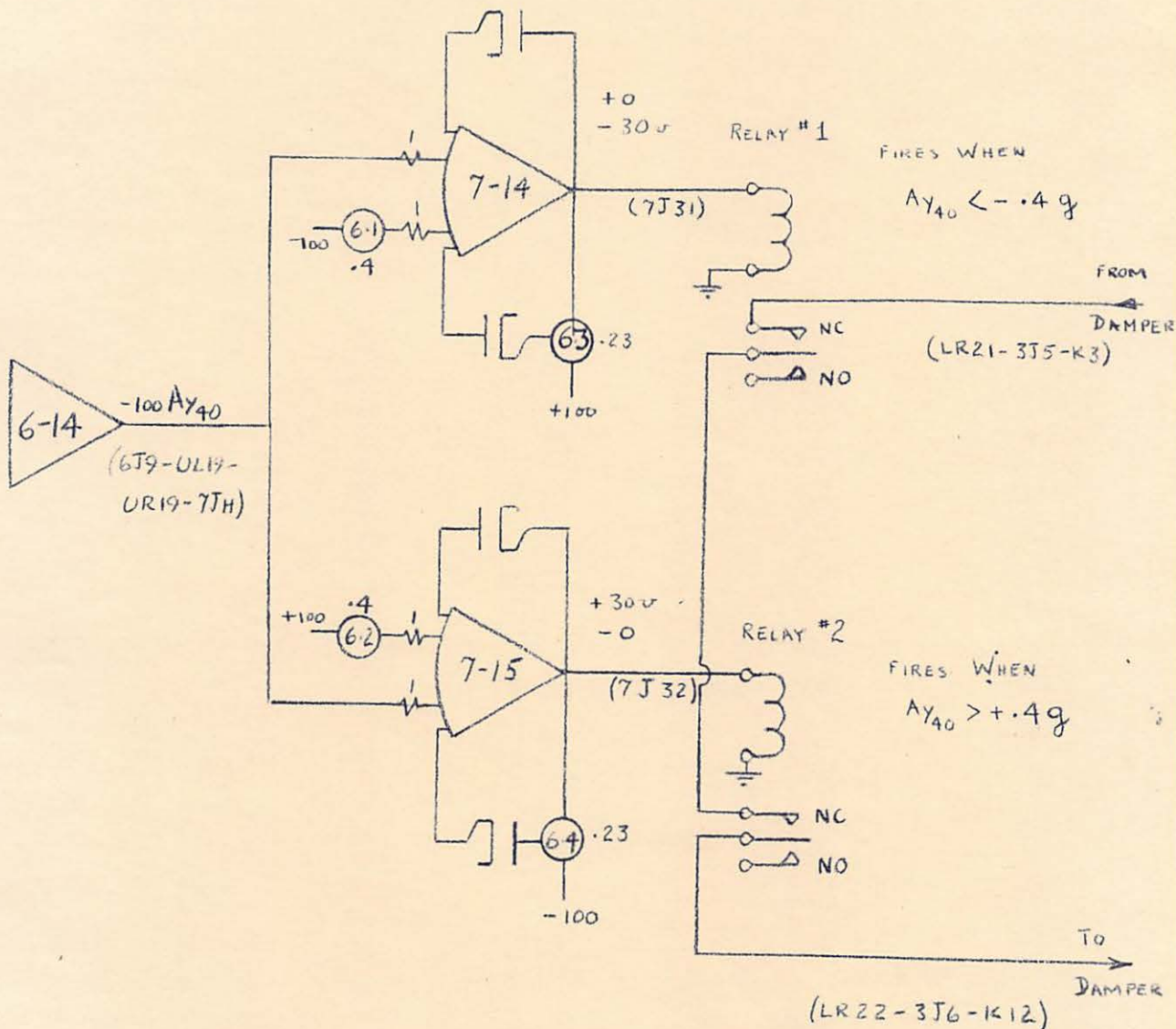
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MALTON - ONTARIO

TECHNICAL DEPARTMENT

AIRCRAFT

C-105

RATE of TURN and
COMPASS HEADING

REPORT NO. _____

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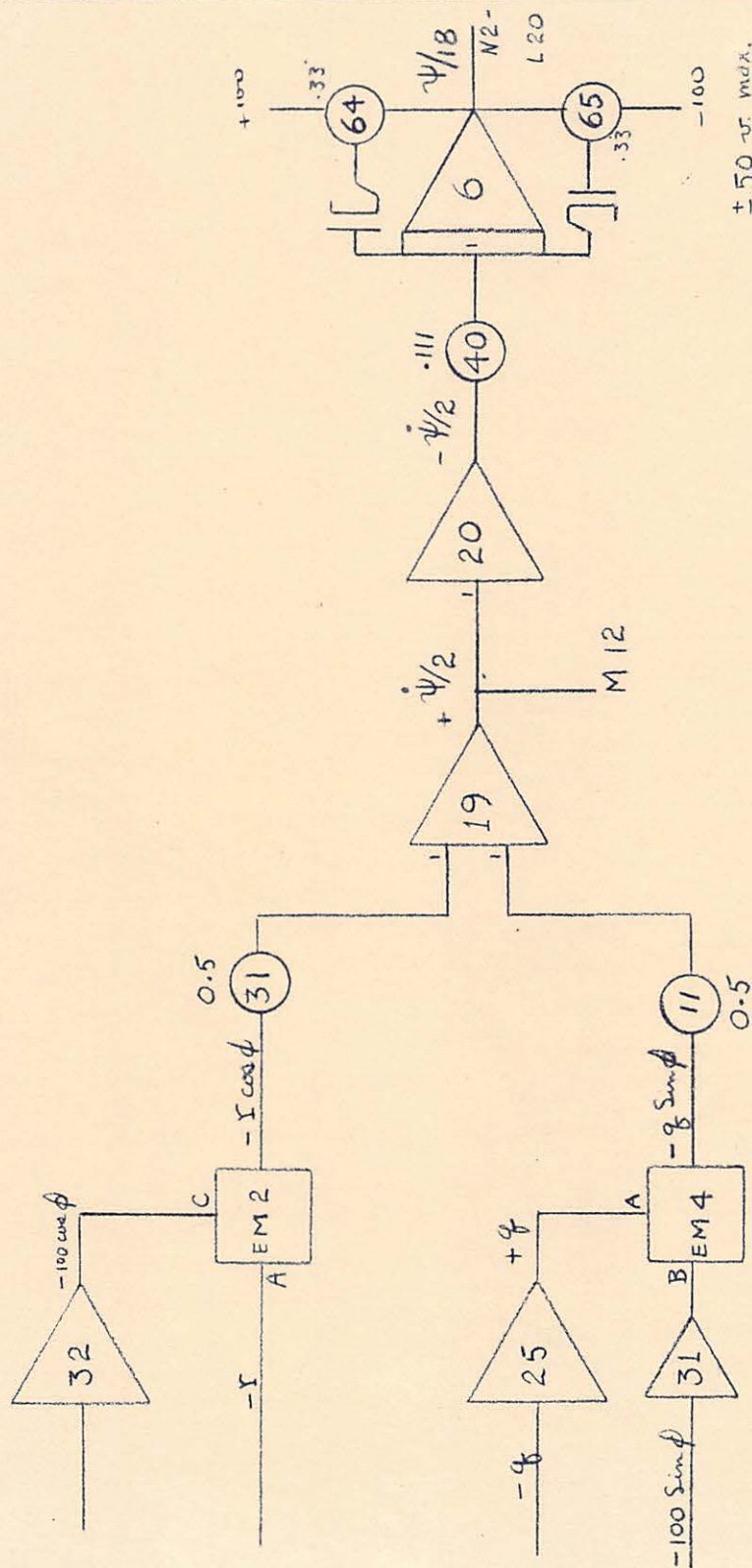
DATE

R. J. D. ...

JAN 14/58

CHECKED BY

DATE



AIRCRAFT:

C105

SIMULATOR,

PREPARED BY

DATE _____

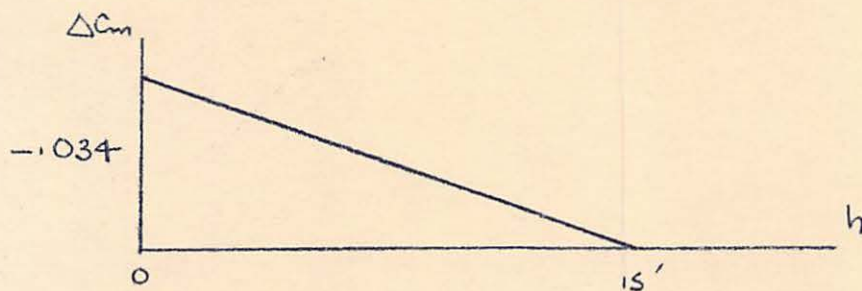
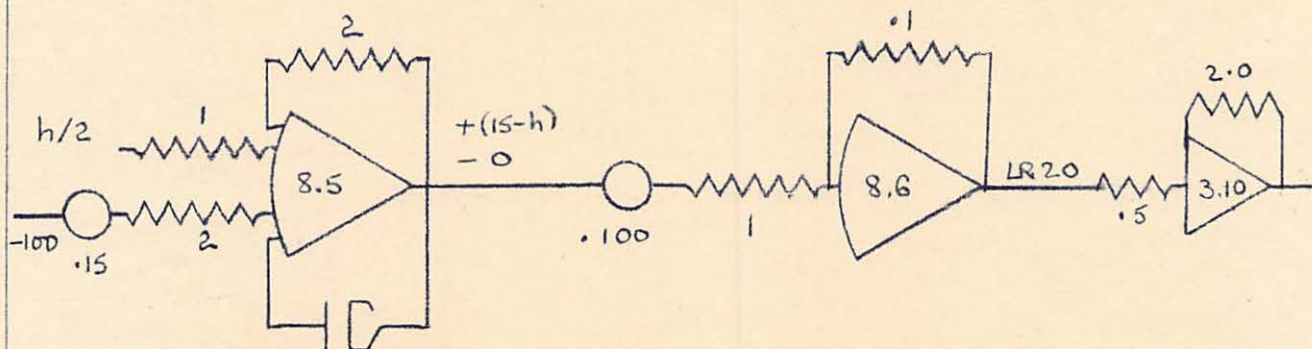
D. V. Foster

Jan 57

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DATE _____

GROUND EFFECT ON PITCHING MOMENT





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MALTON, ONTARIO

TECHNICAL DEPARTMENT

AIRCRAFT:

C-105

SIMULATOR.

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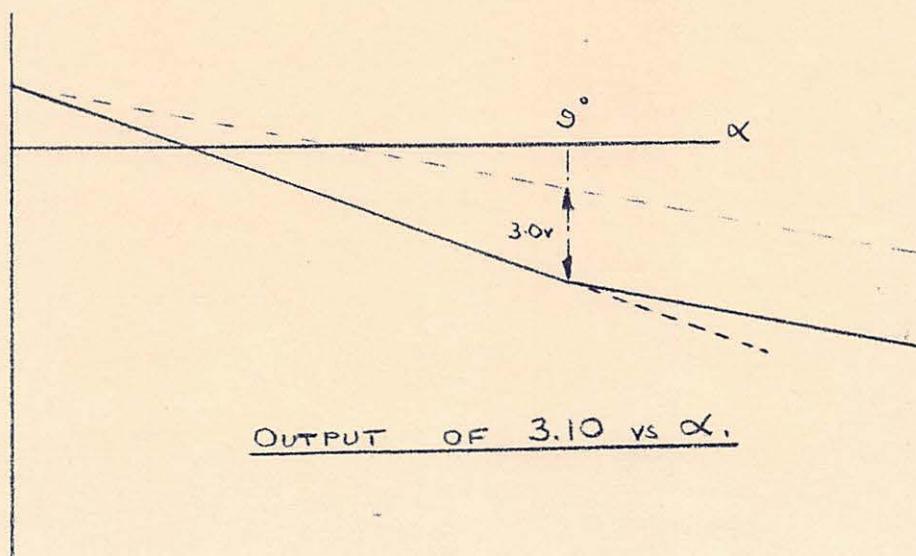
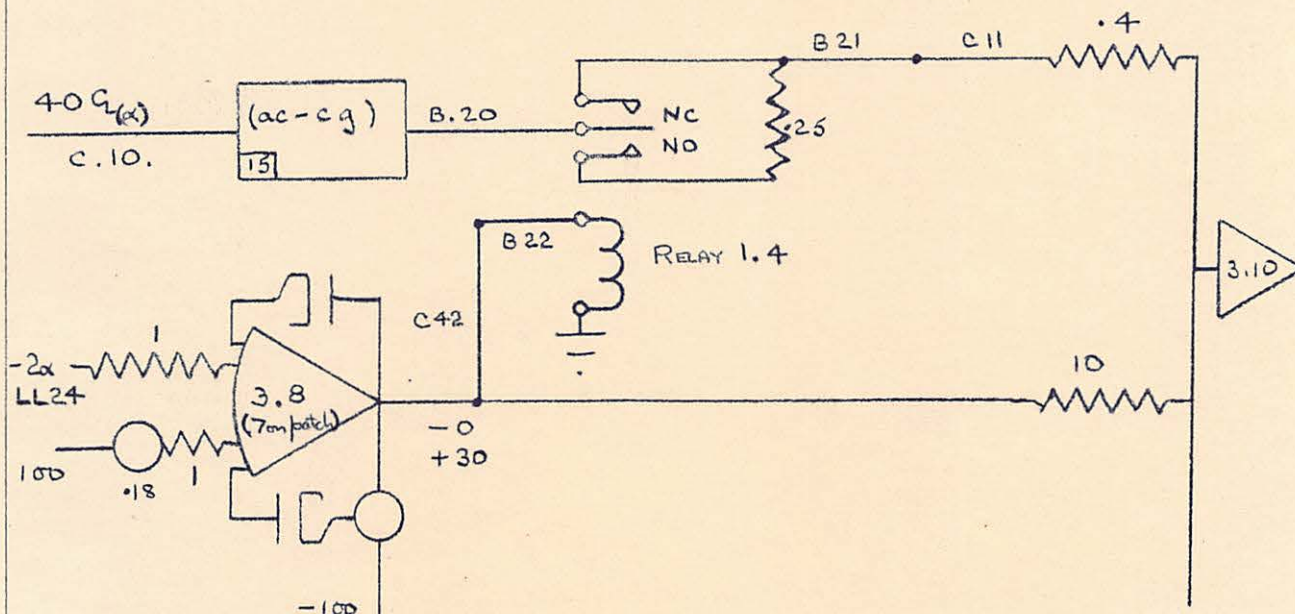
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HIGH INCIDENCE EFFECTS ON PITCHING MOMENT.



OUTPUT OF 3.10 vs α .



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MALTON - ONTARIO

TECHNICAL DEPARTMENT

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SHEET NO. _____

AIRCRAFT:

C-105

HIGH INCIDENCE

EFFECTS, ON C_{np} , C_{lp} .

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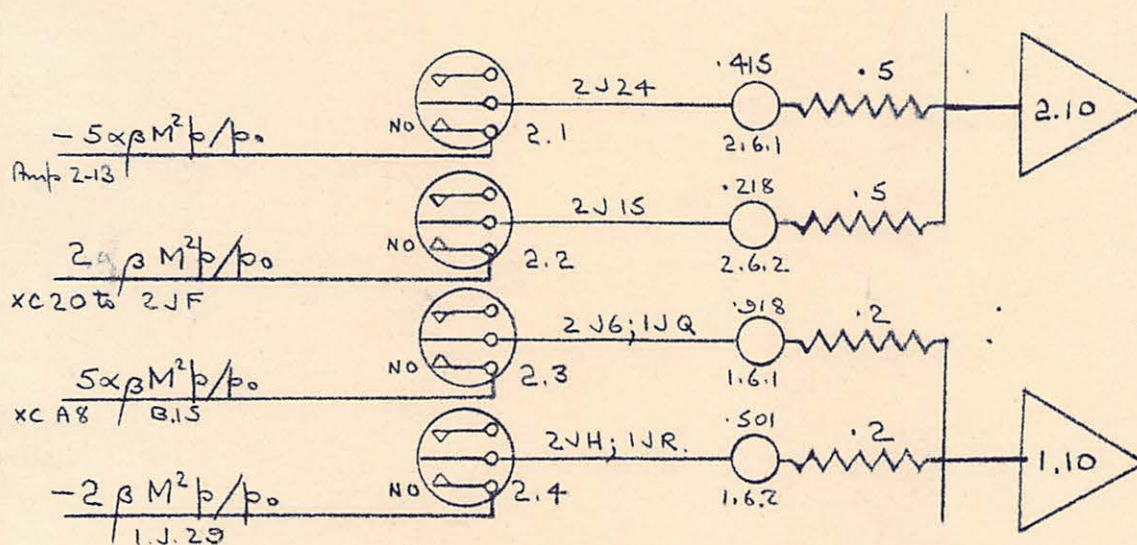
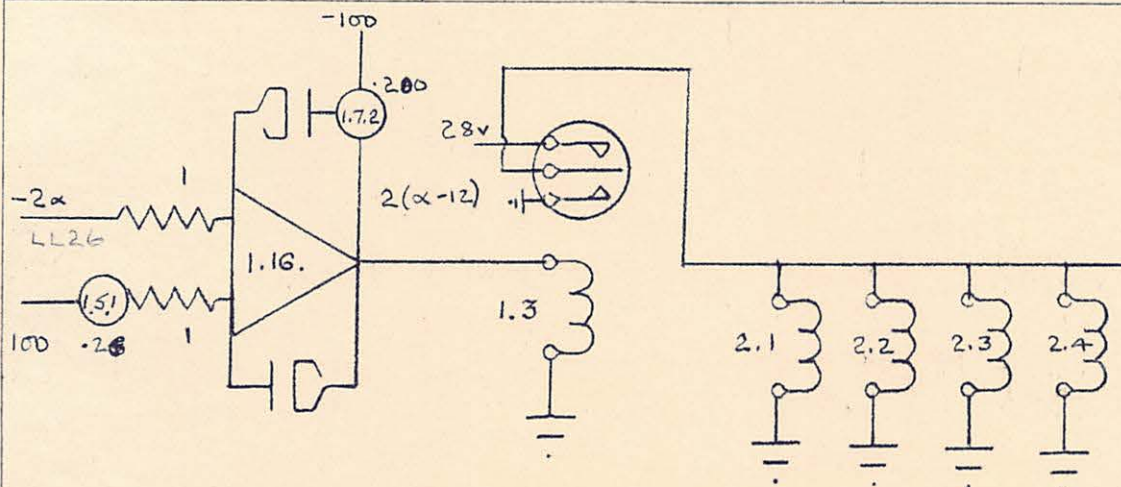
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DATE





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REPORT No. _____

SHEET No. _____

AIRCRAFT:

C-105

SIMULATOR.

PREPARED BY

D. J. Foster

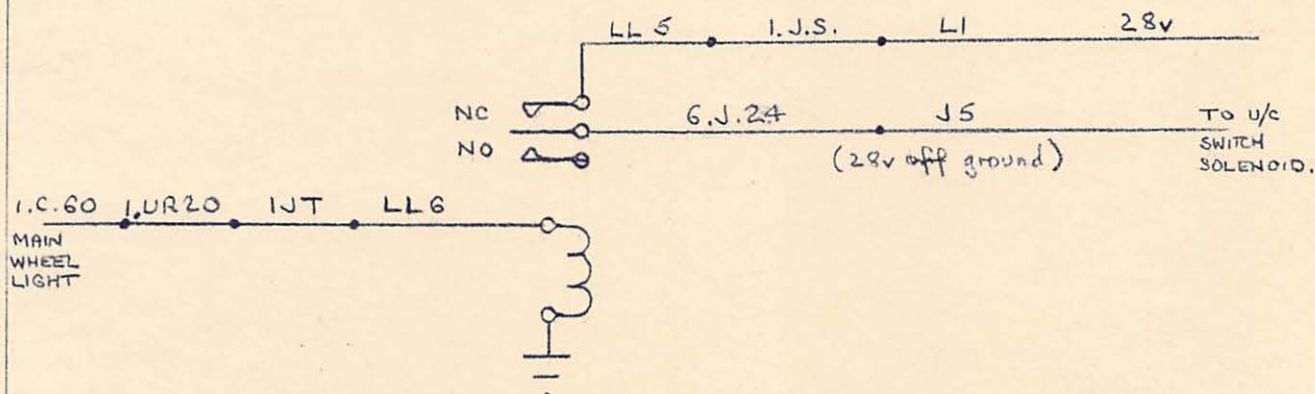
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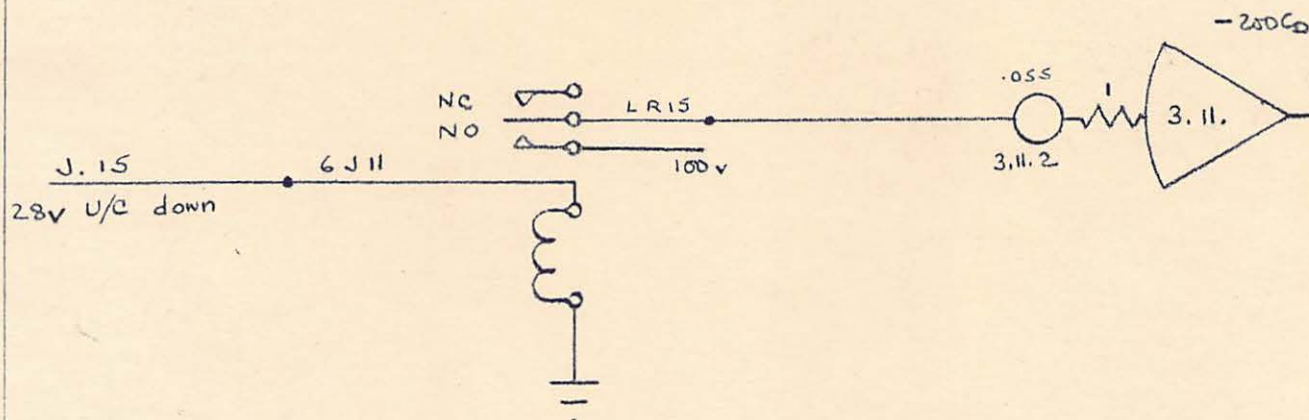
Jan 57.

DATE

CIRCUIT TO FREE UNDERCARRIAGE SWITCH IN THE AIR.



DRAG INCREMENT DUE TO UNDERCARRIAGE.





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MALTON - ONTARIO

TECHNICAL DEPARTMENT

AIRCRAFT:

RUDDER HINGE MOMENT CKT.

REPORT NO. _____

SHEET NO. _____

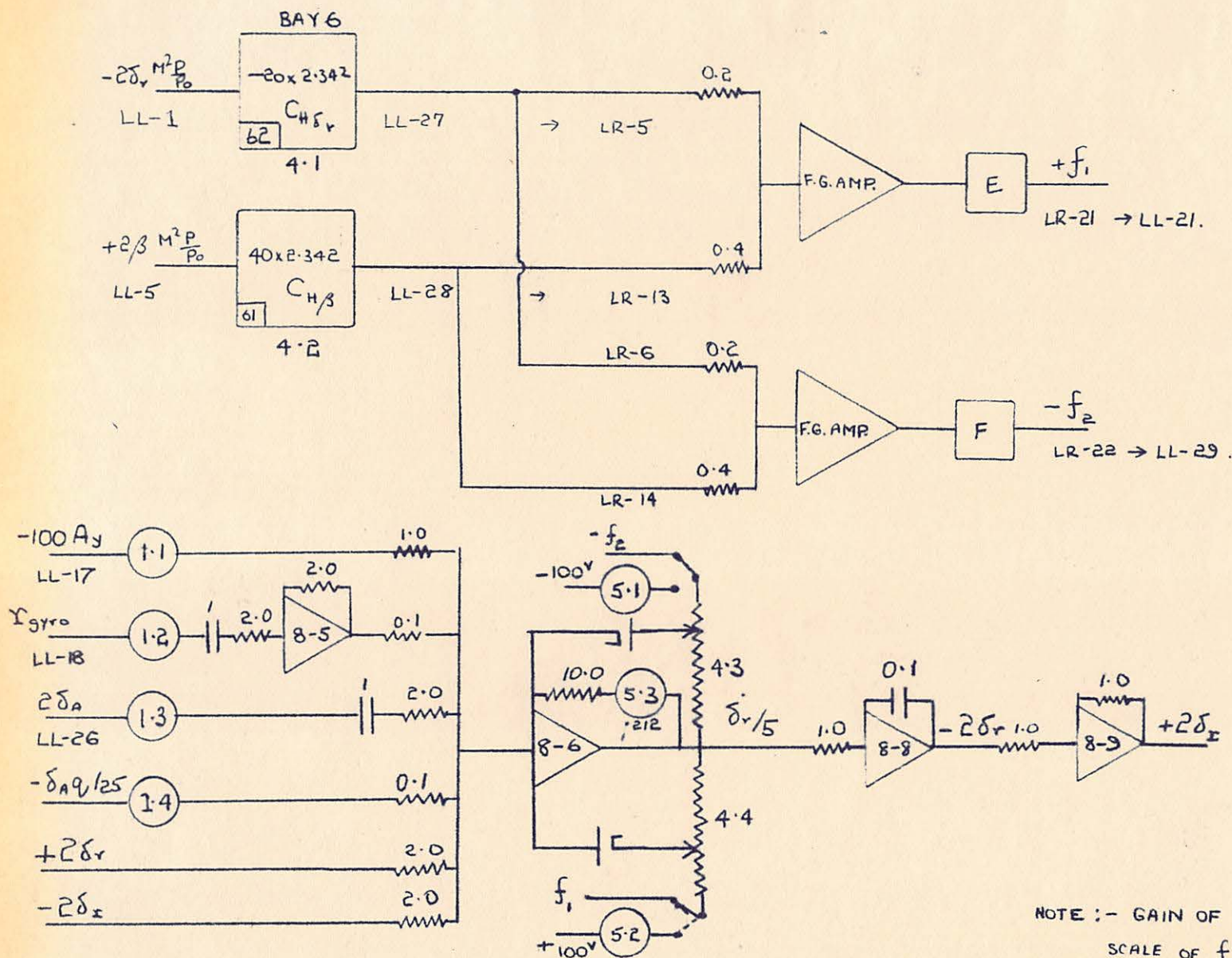
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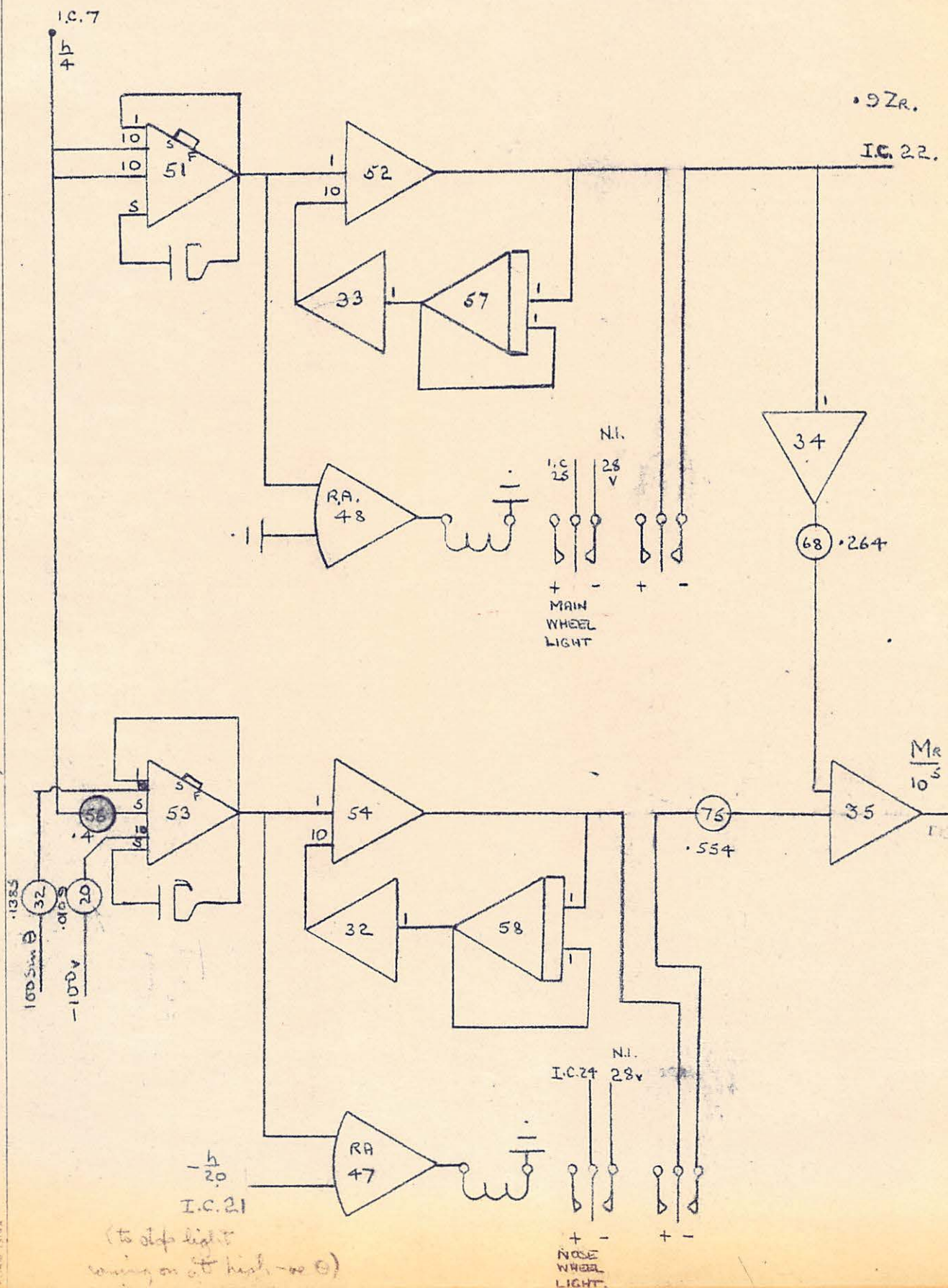
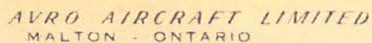
R. A. IRWIN .

DATE

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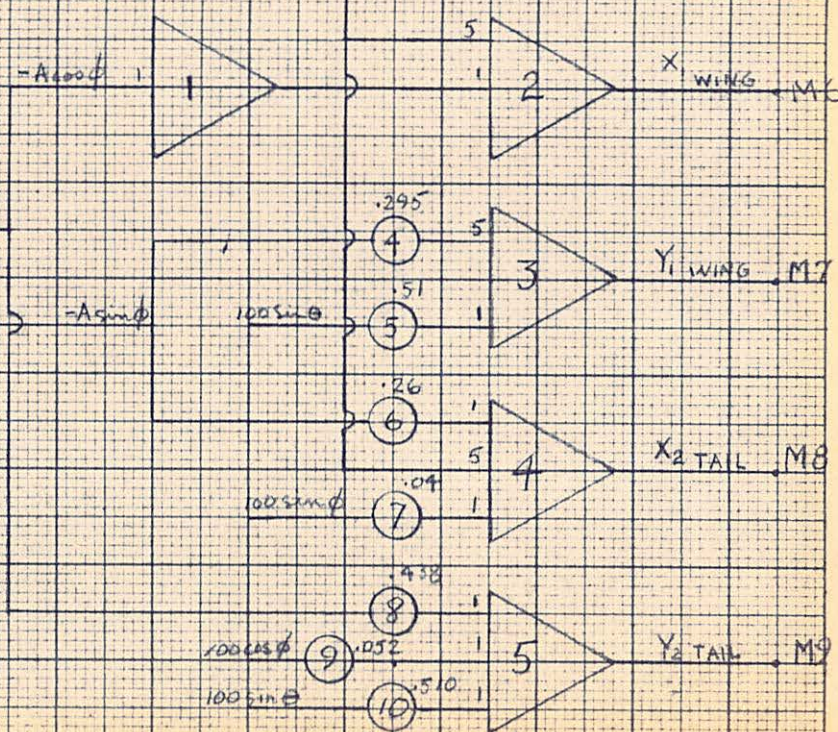
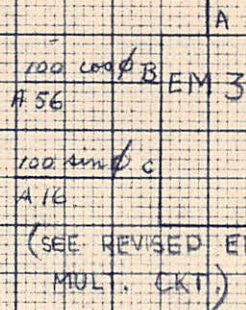
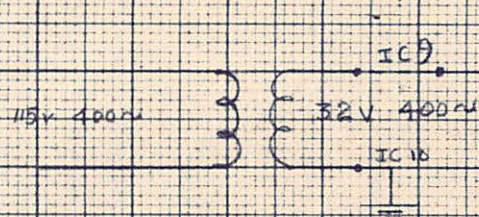
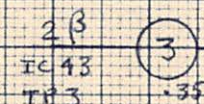
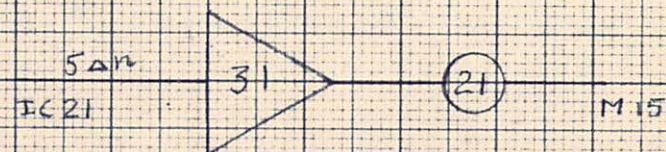
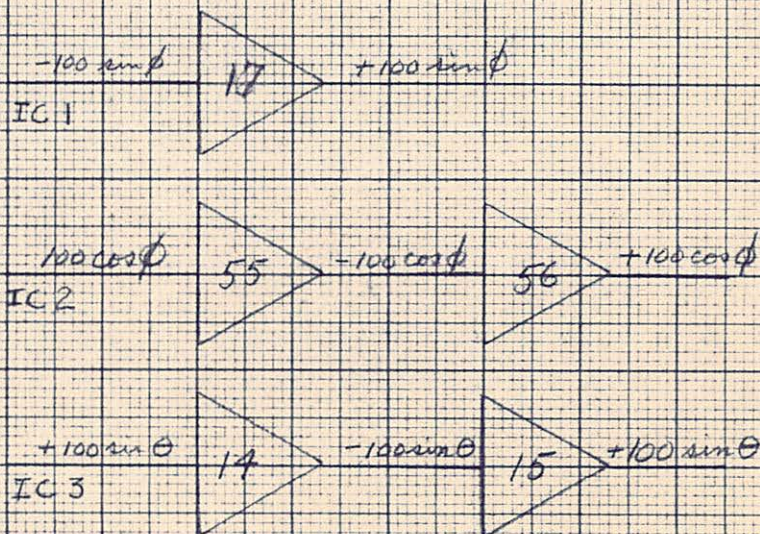
DATE





B-1 RIG INSTRUMENT CIRCUIT

ISSUE 2 KNO
 JAN 26/58



TECHNICAL DEPARTMENT (Aircraft)

AIRCRAFT:

Arrow Simulator

Face of Servo Rack

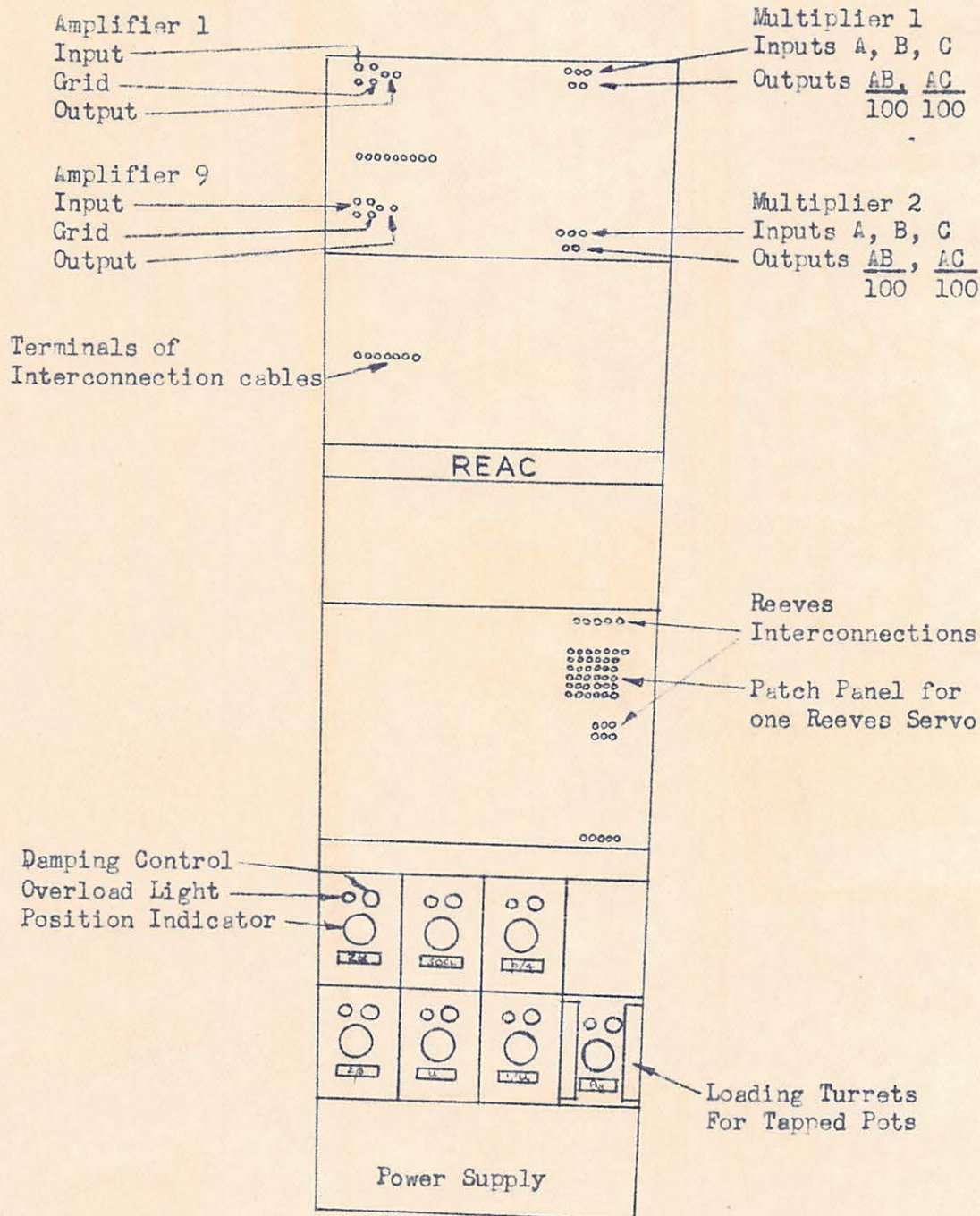
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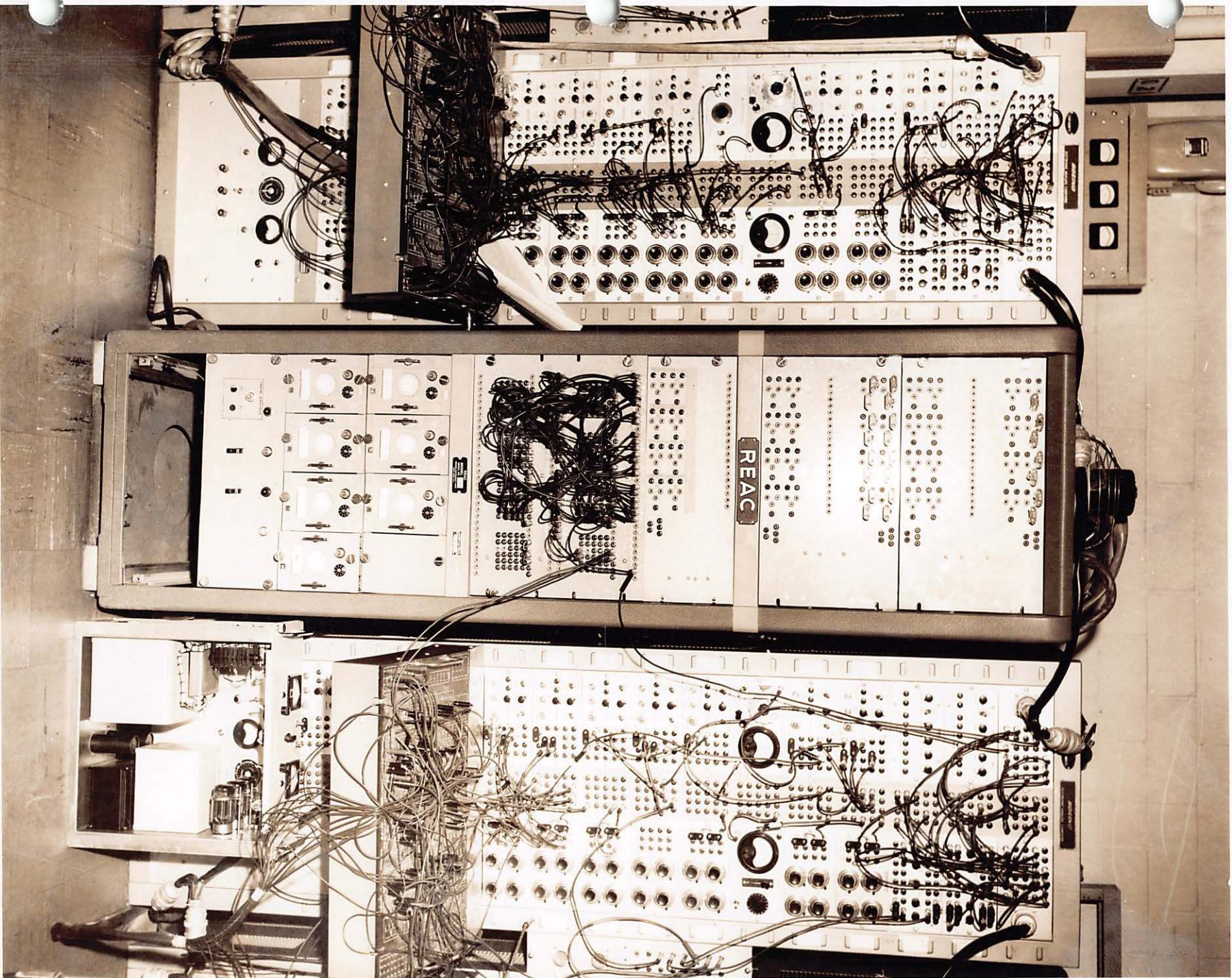
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TECHNICAL DEPARTMENT (Aircraft)

REPORT NO 70/Sim/14

SHEET NO 4.1

AIRCRAFT

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DATE

Arrow Simulator

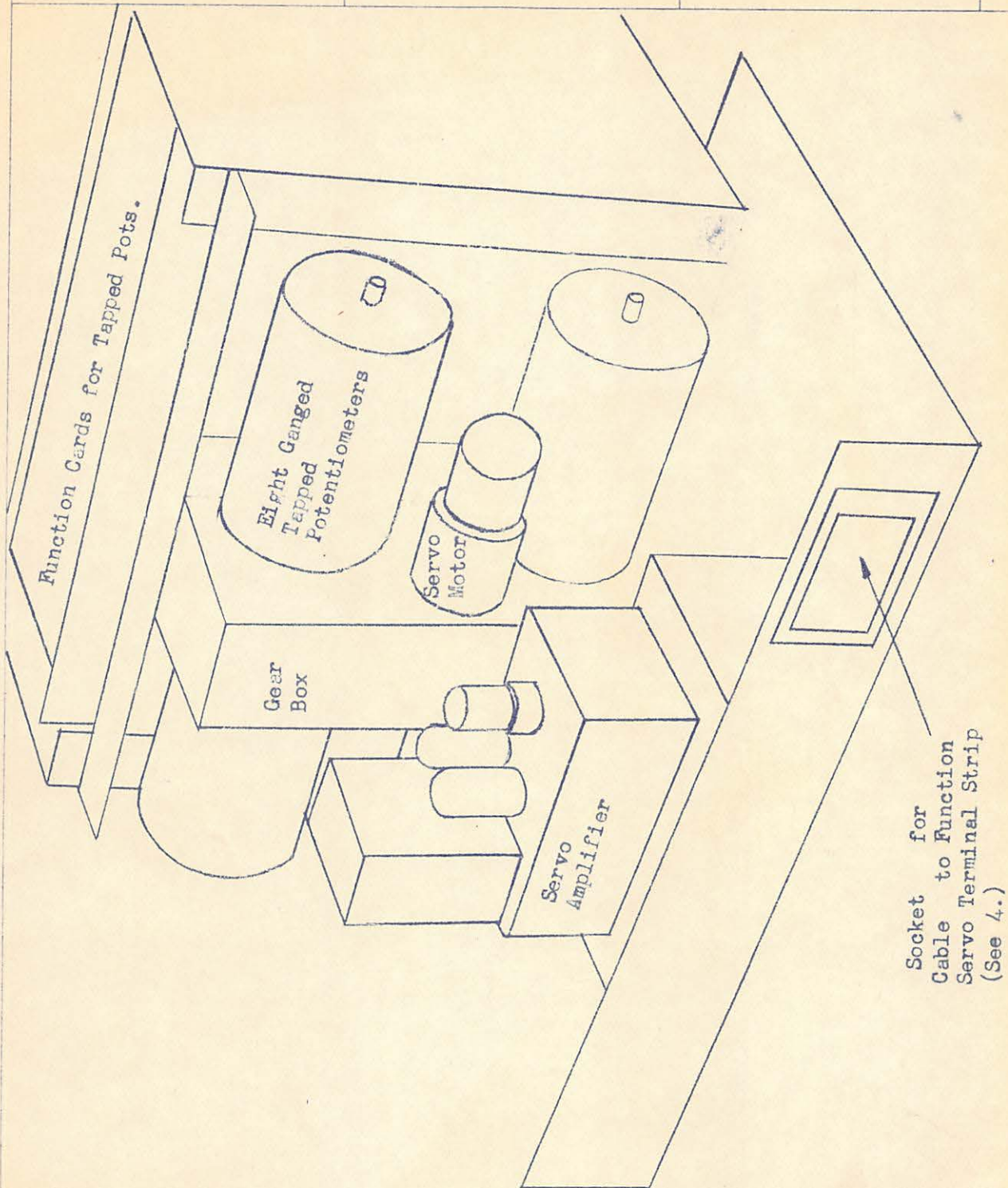
Function Cards Rack

D.J. Foster

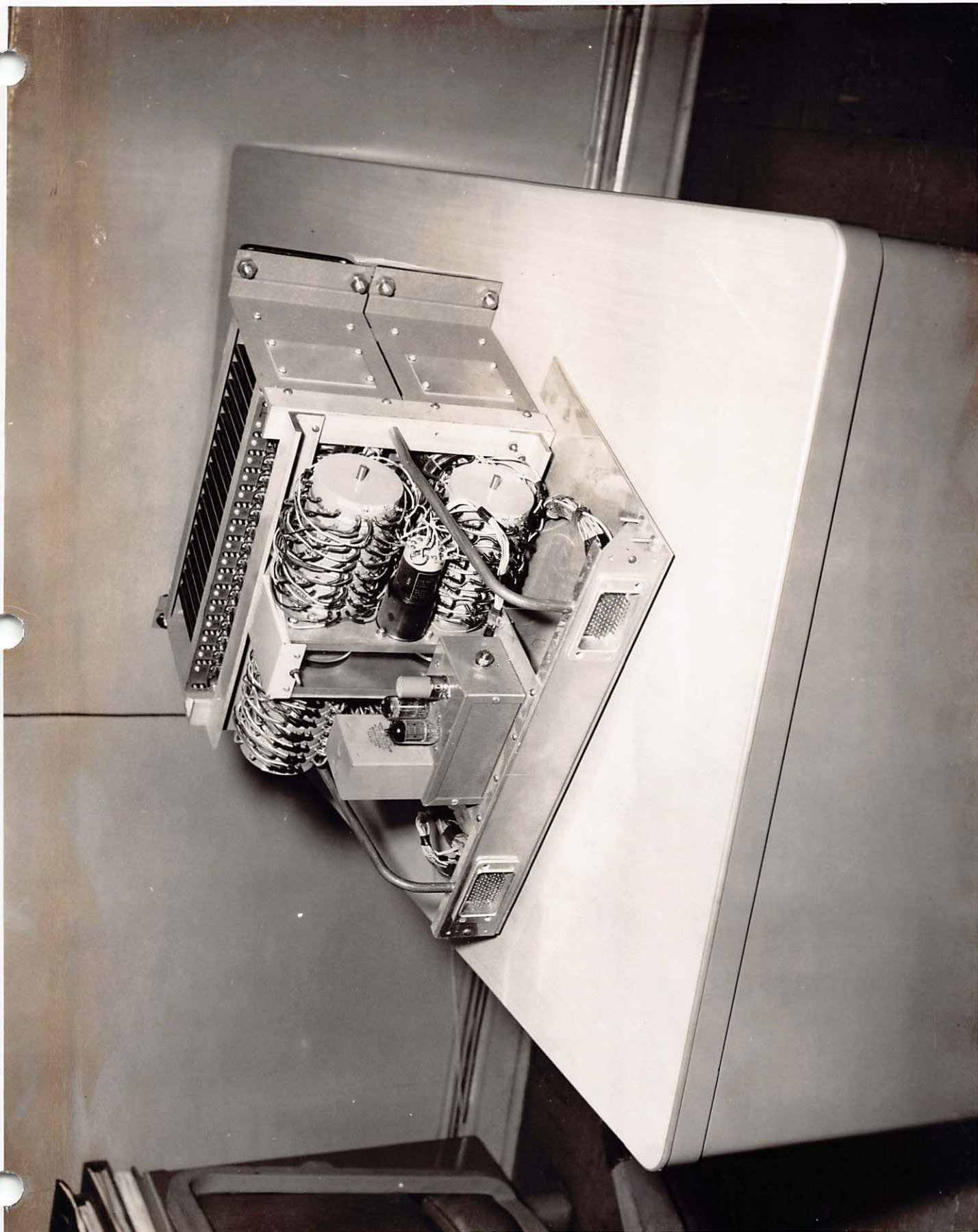
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Front view of Function Card Rack



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MALTON - ONTARIO

TECHNICAL DEPARTMENT

AIRCRAFT

Arrow Simulator

Function Cards Rack

REPORT NO. 70/Sim/14

SHEET NO. 4.3

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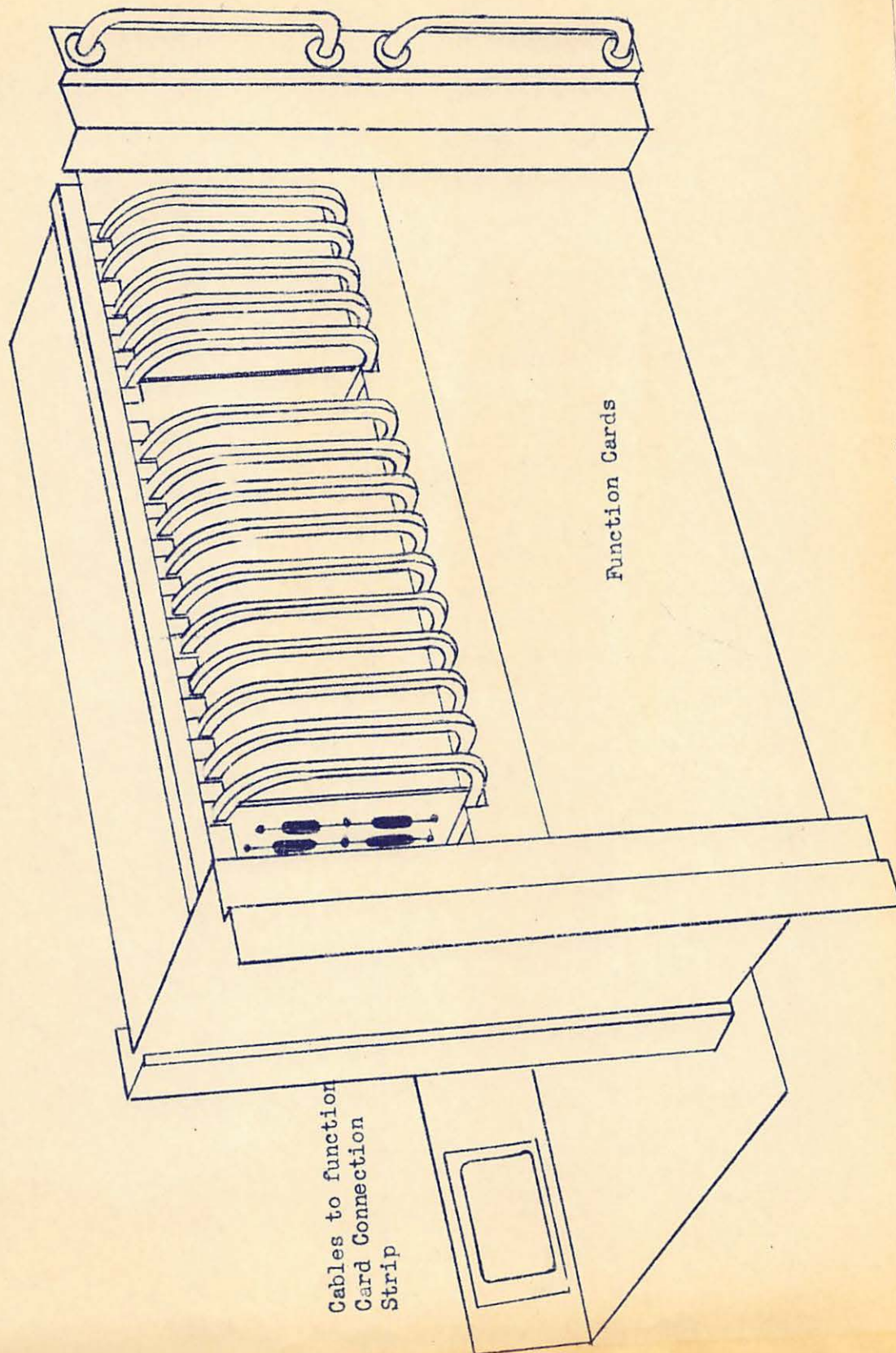
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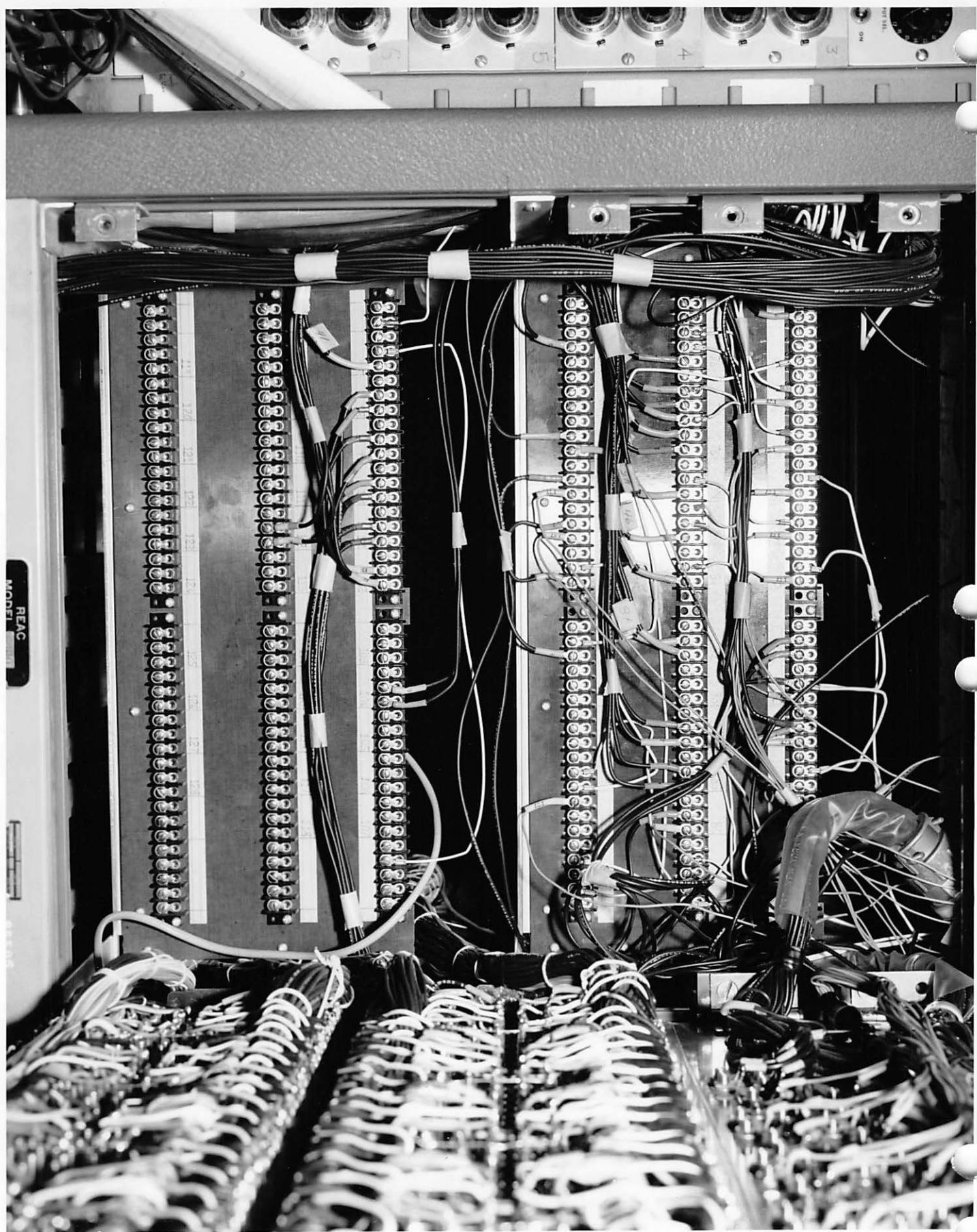
Rear view of Function Card Rack



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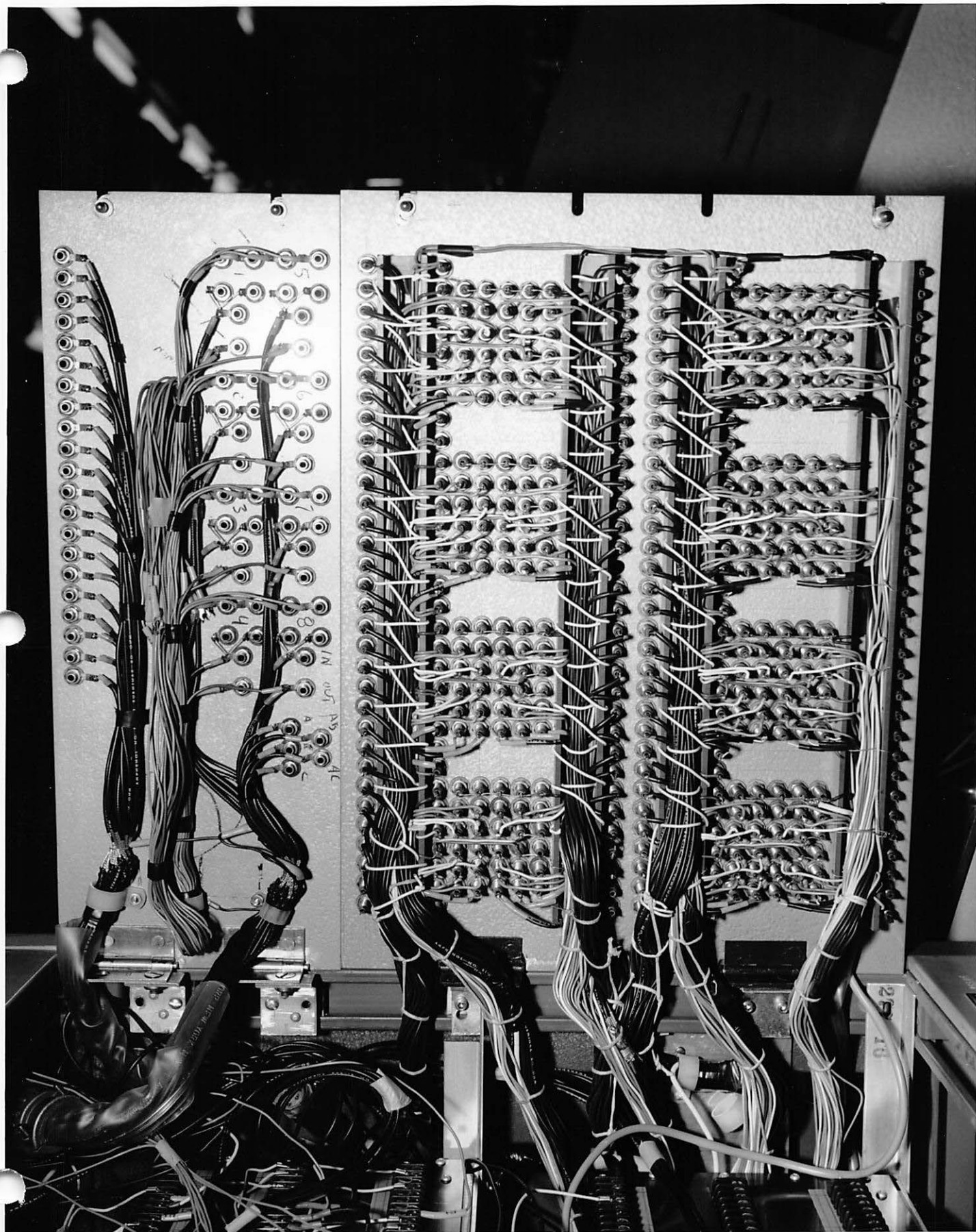
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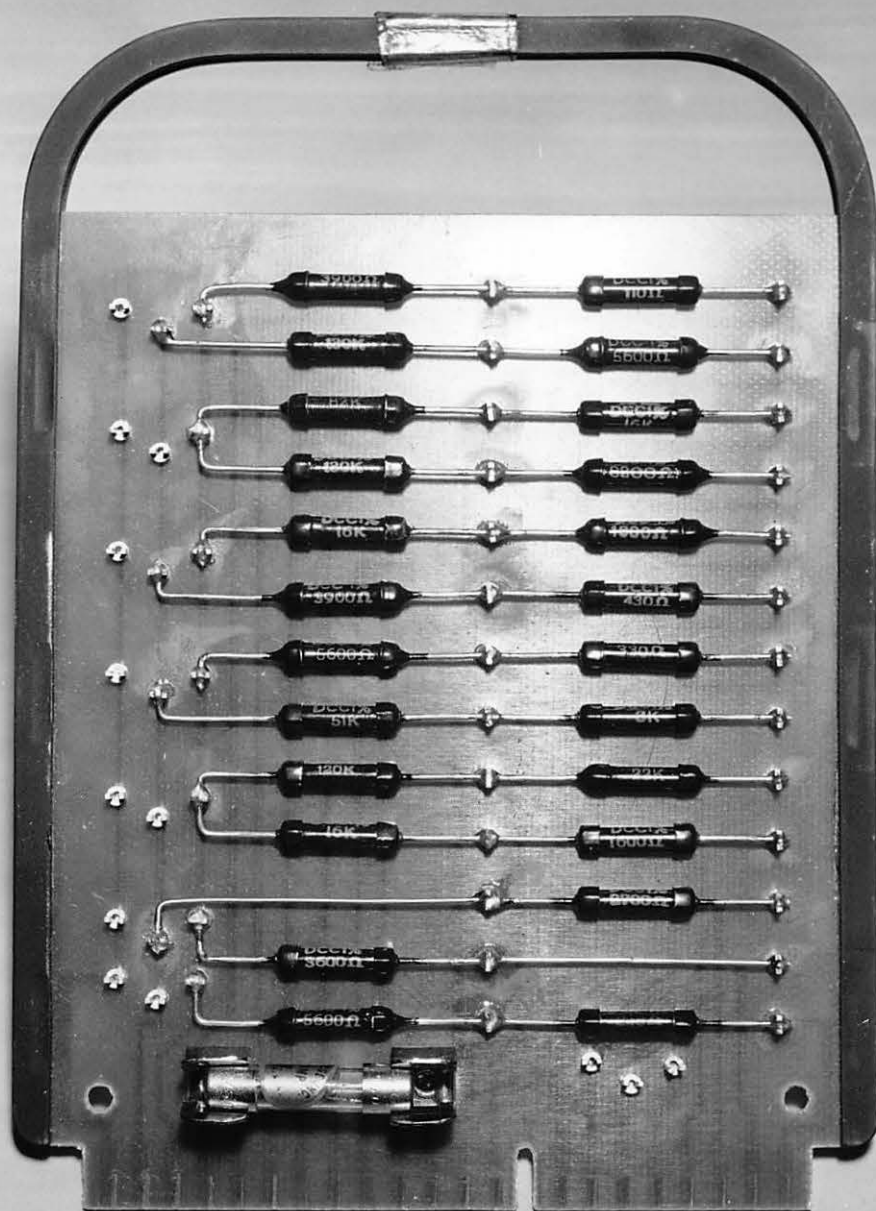
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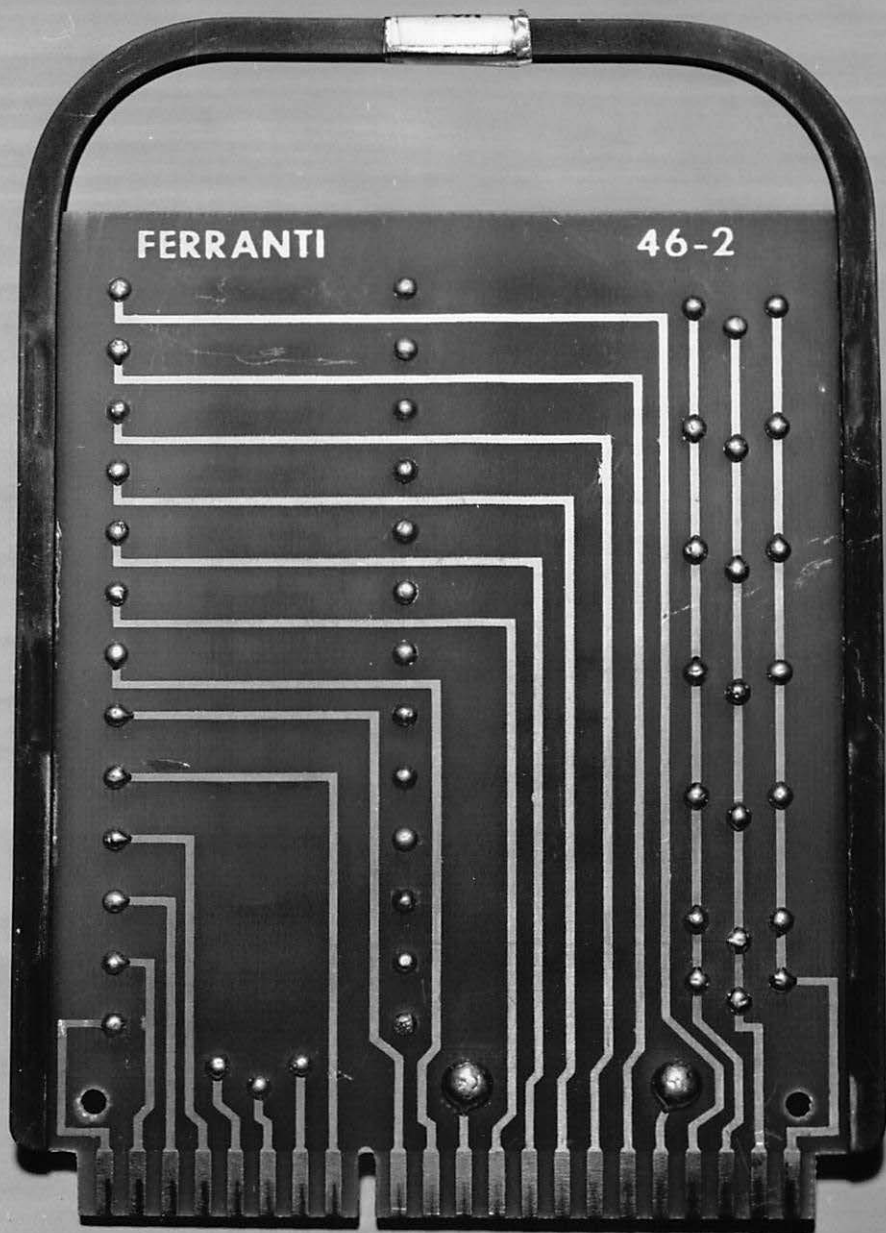
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